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Electric field reconstruction in the image plane of a high-contrast coronagraph using a set of pinholes around the Lyot plane

Amir Give'on

Jet Propulsion Laboratory
California Institute of Technology, Pasadena CA

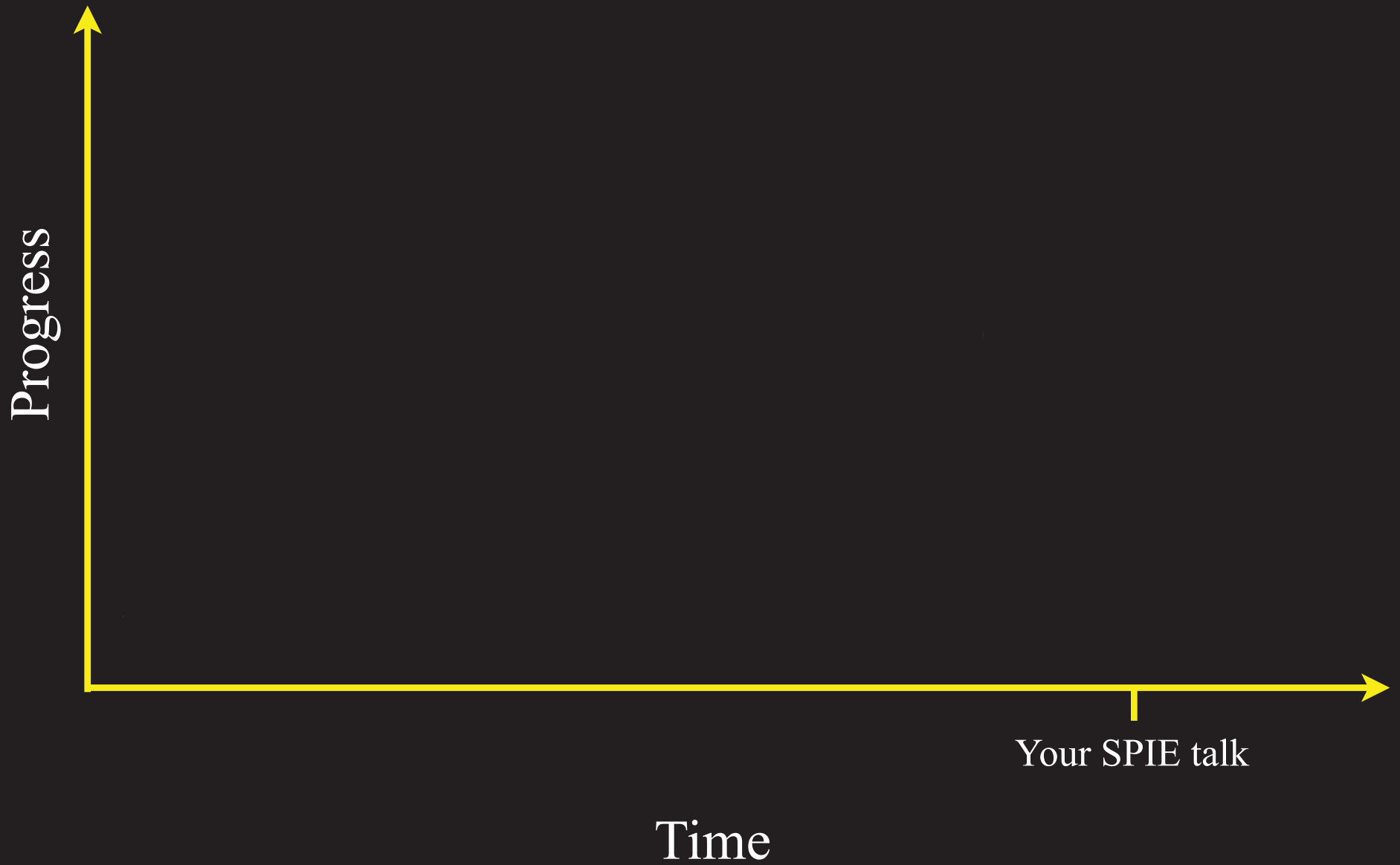
Co-authors: Brian Kern, Stuart Shaklan, Kent Wallace, Charley Noecker

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Monday, June 25, 2012

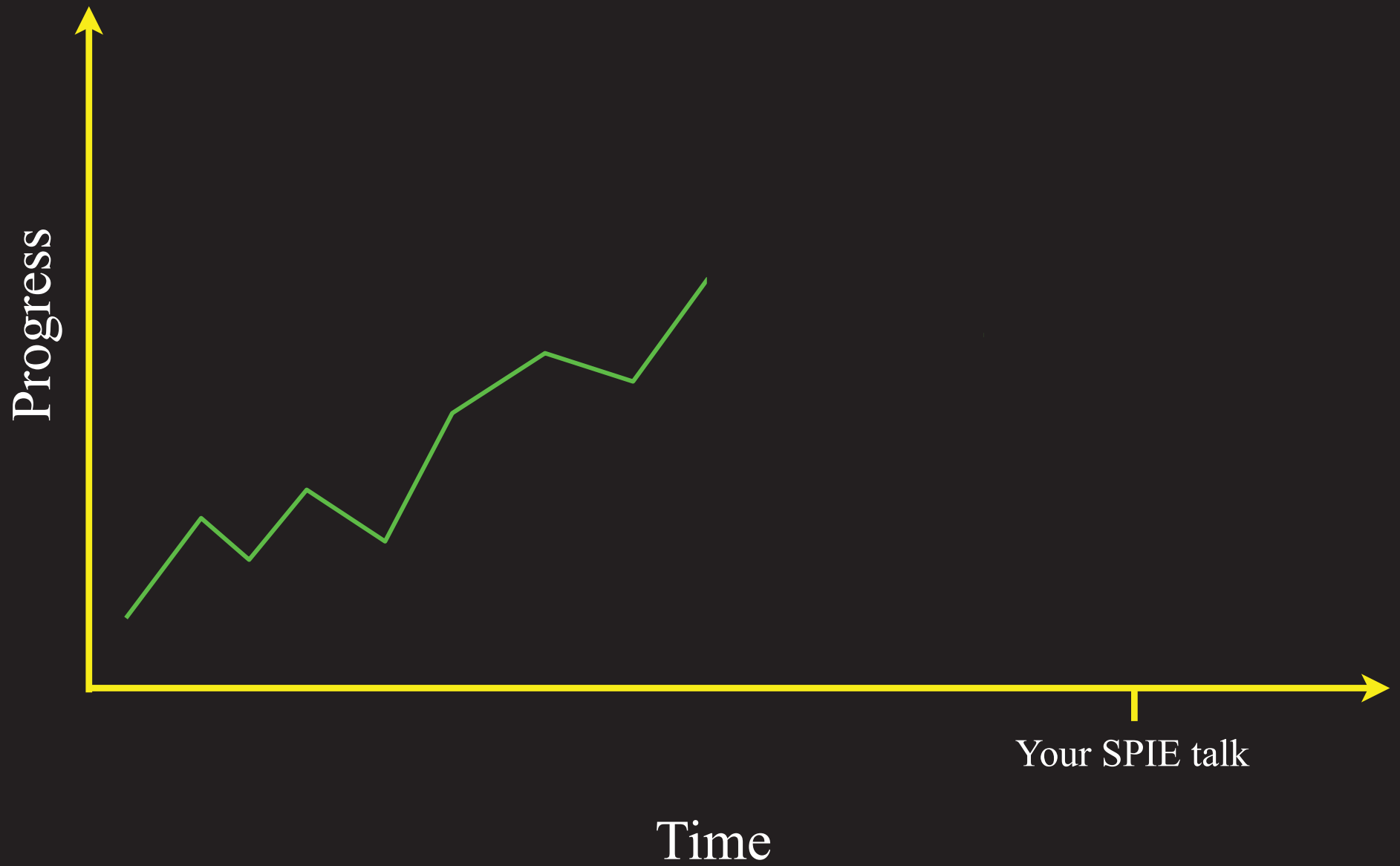


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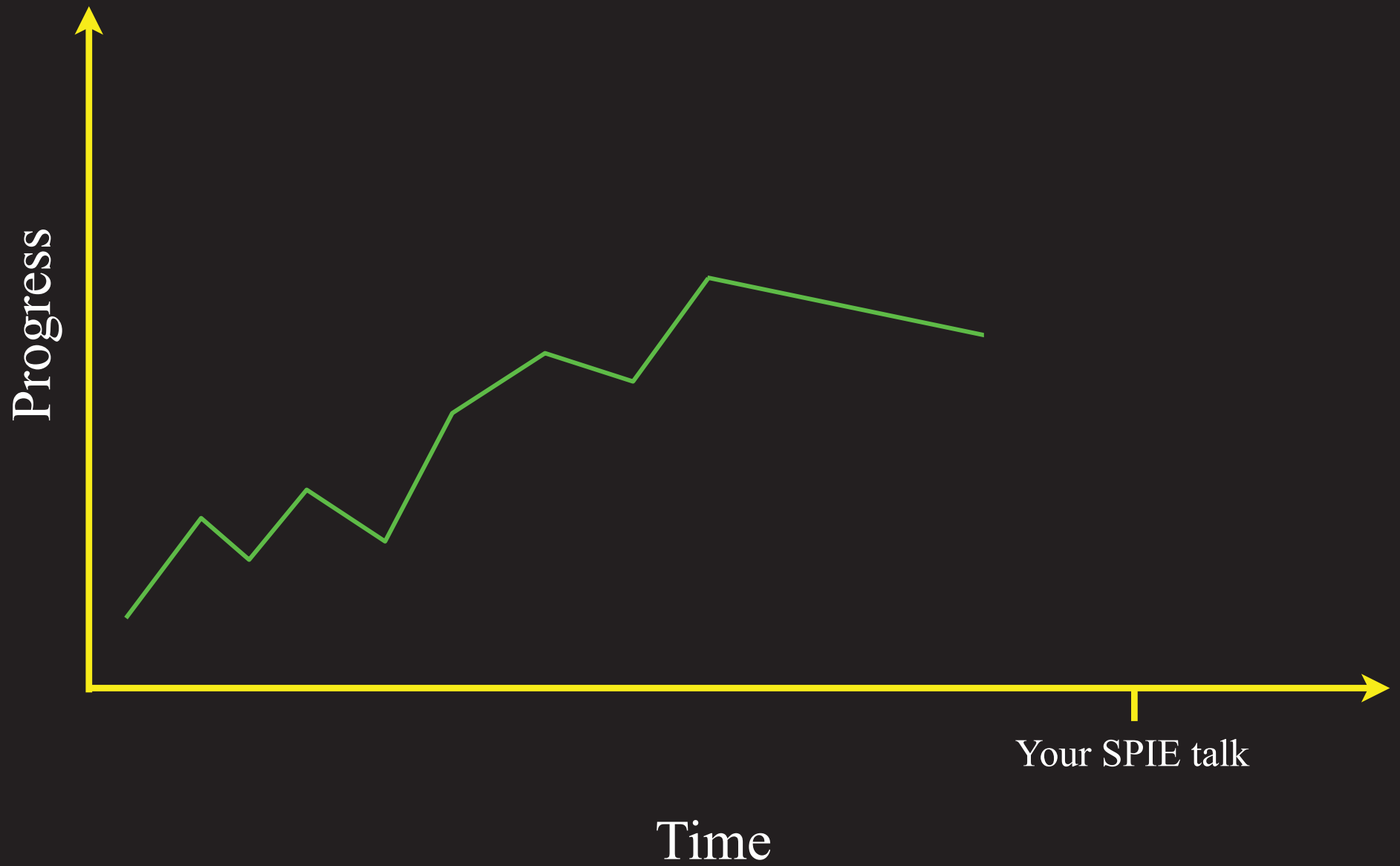


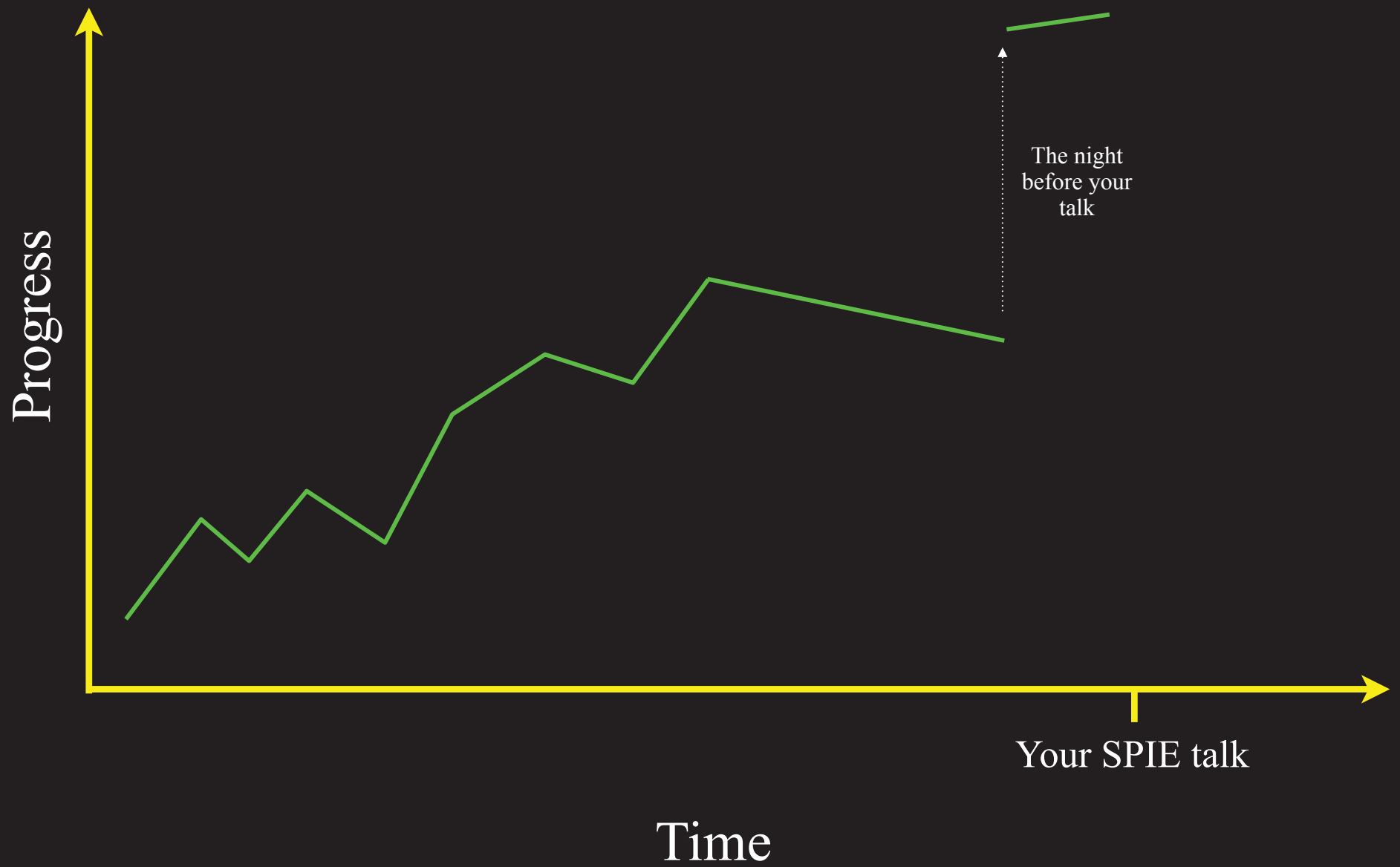
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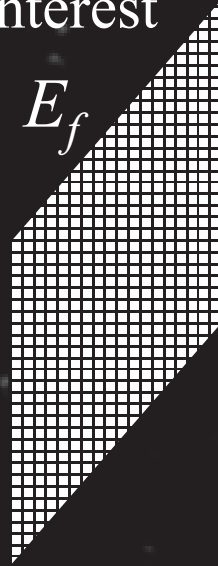
Electric Field Conjugation

DM plane



Plane of
interest

E_f



$E_{abr+ideal}$

$$E_f =$$



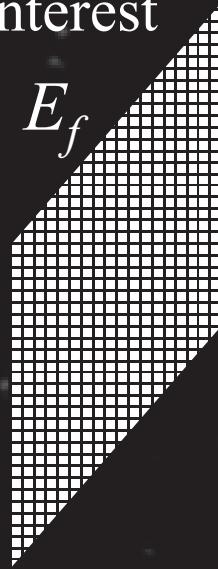
Electric Field Conjugation

DM plane



Plane of
interest

E_f



$$E_f = E_{abr+ideal}$$



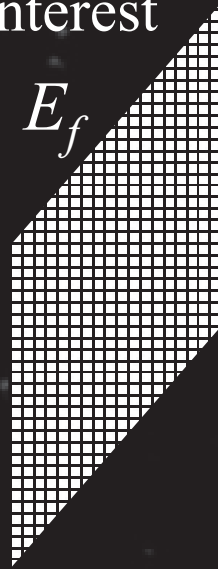
Electric Field Conjugation

DM plane



Plane of
interest

E_f



$$E_f = E_{abr+ideal}$$



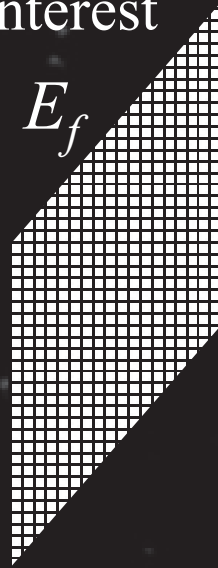
Electric Field Conjugation

DM plane



Plane of
interest

E_f



$$E_f = E_{abr+ideal} + E_{DM}$$

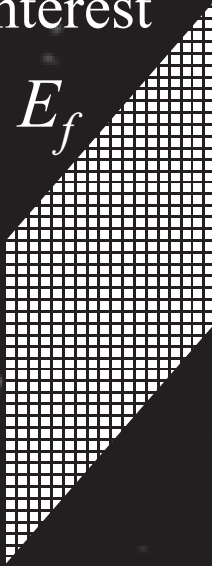


Electric Field Conjugation

DM plane



Plane of
interest



Find the shape of the DM such
that its effect in the plane of
interest **negates** the electric field
present in this plane due to the
coronagraph and the aberrations

$$E_f = E_{abr+ideal} + E_{DM} = 0$$

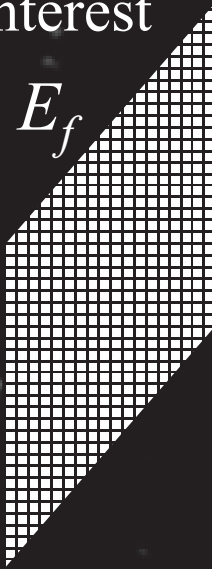


Electric Field Conjugation

DM plane



Plane of
interest



Find the shape of the DM such
that its effect in the plane of
interest **negates** the electric field
present in this plane due to the
coronagraph and the aberrations

$$E_f = E_{abr+ideal} + E_{DM} = 0$$



Linearize w.r.t
actuators heights



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What shapes on the DM should we use for the probes?

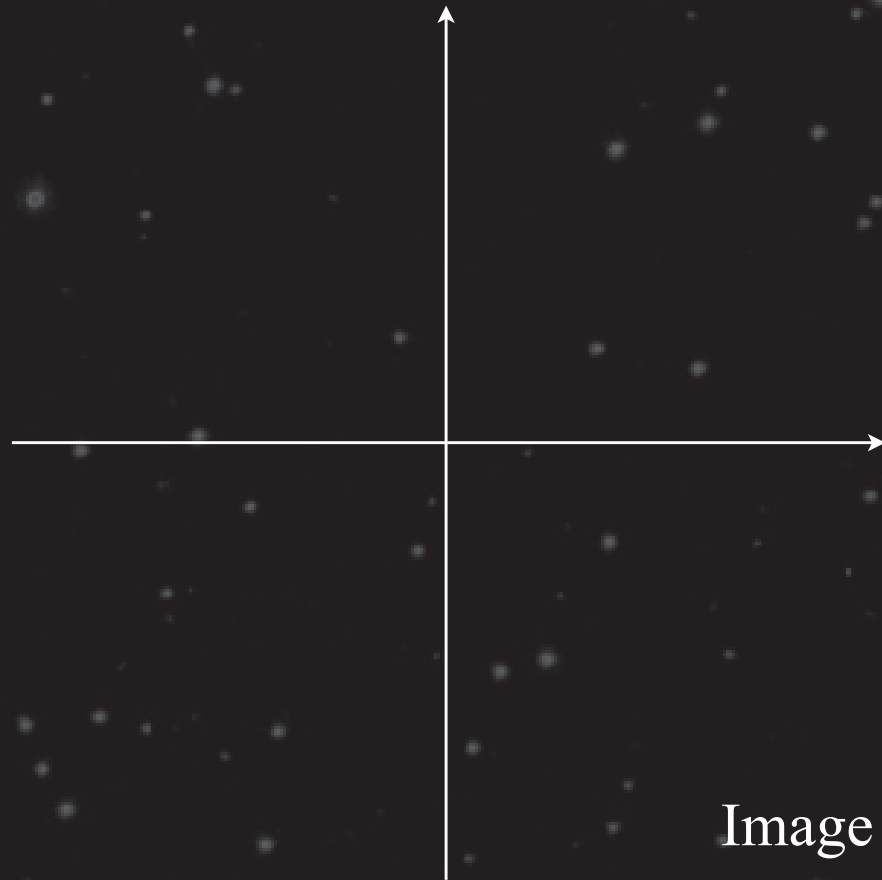
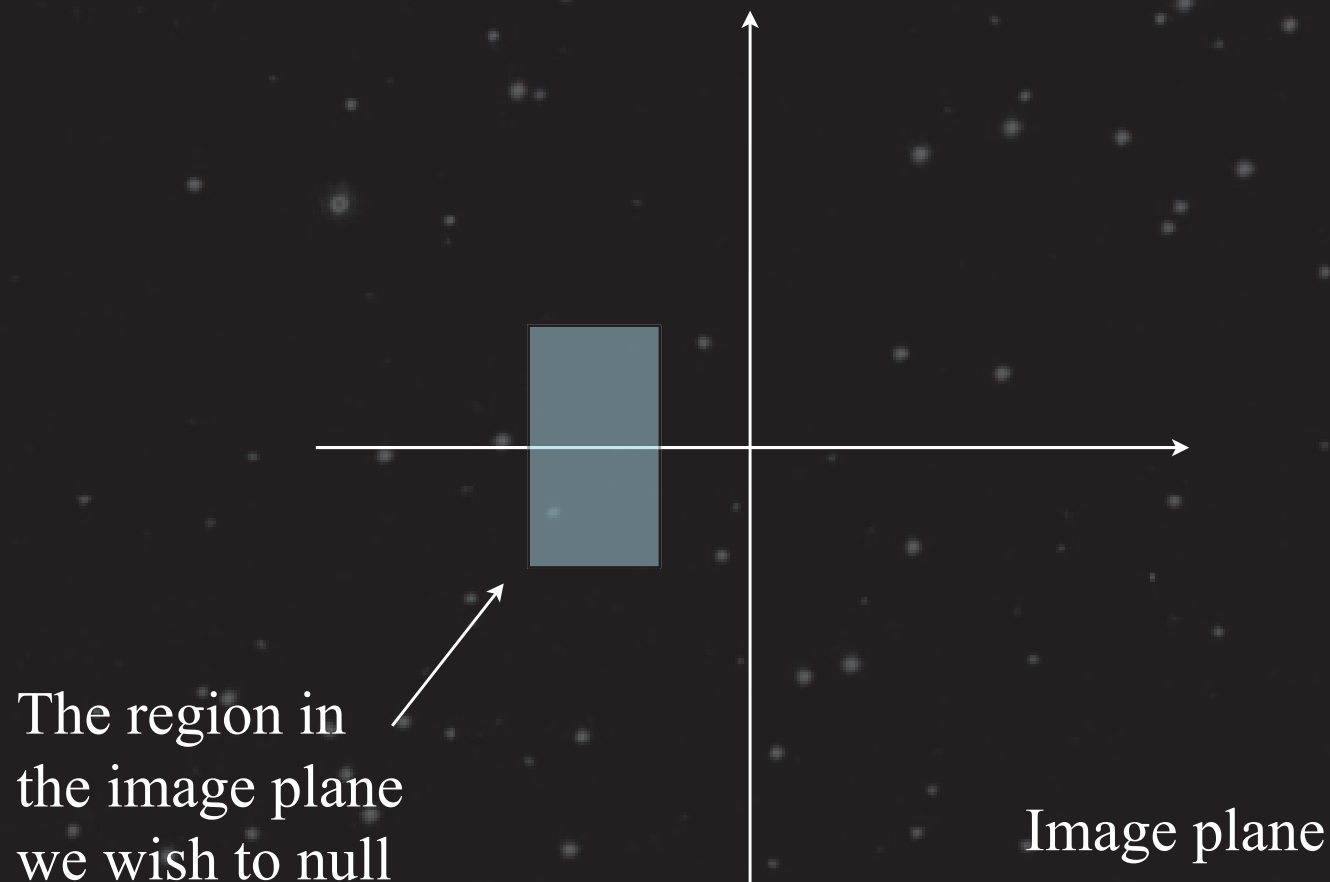


Image plane



What shapes on the DM should we use for the probes?

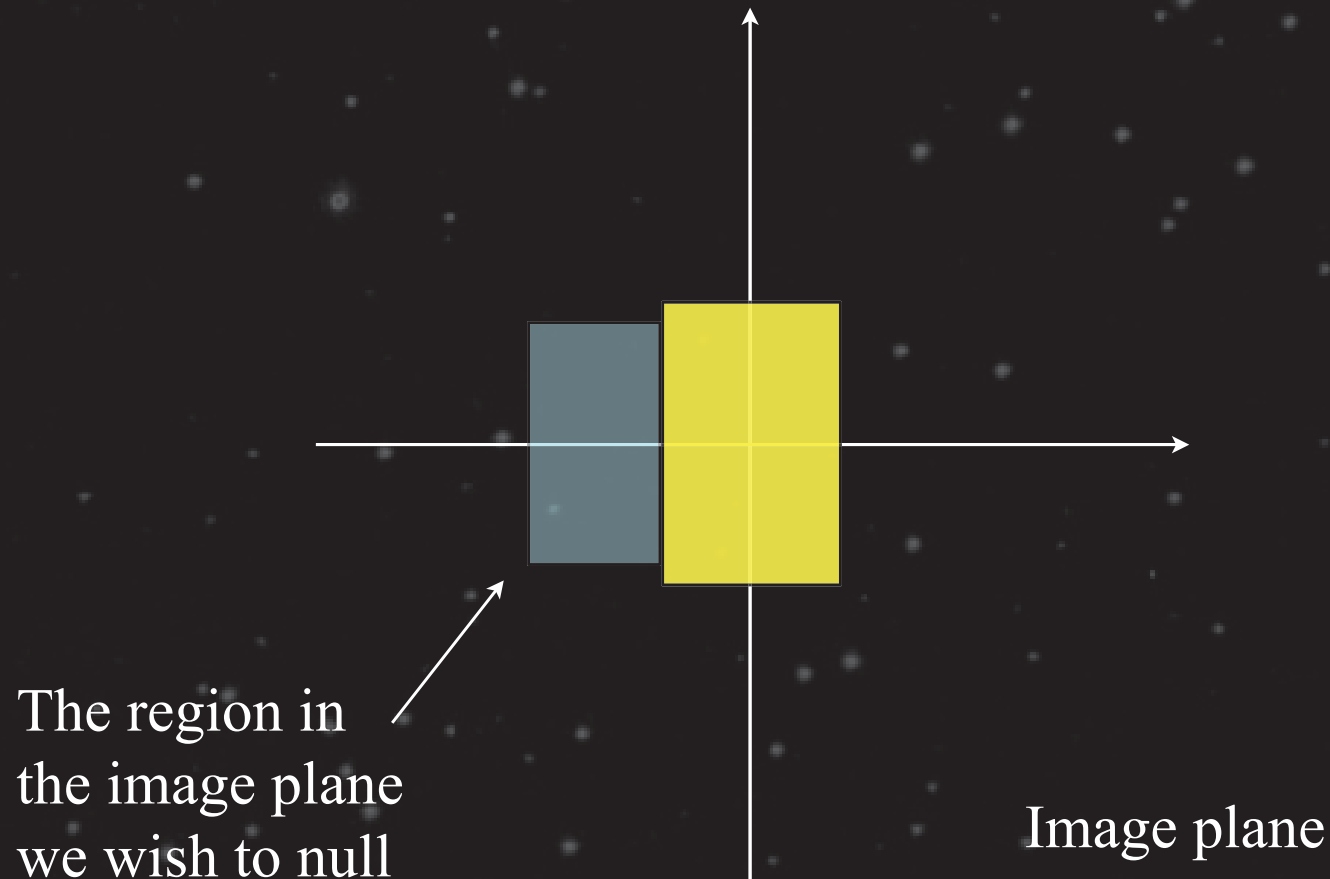
$$DM(x, y) = ?$$





What shapes on the DM should we use for the probes?

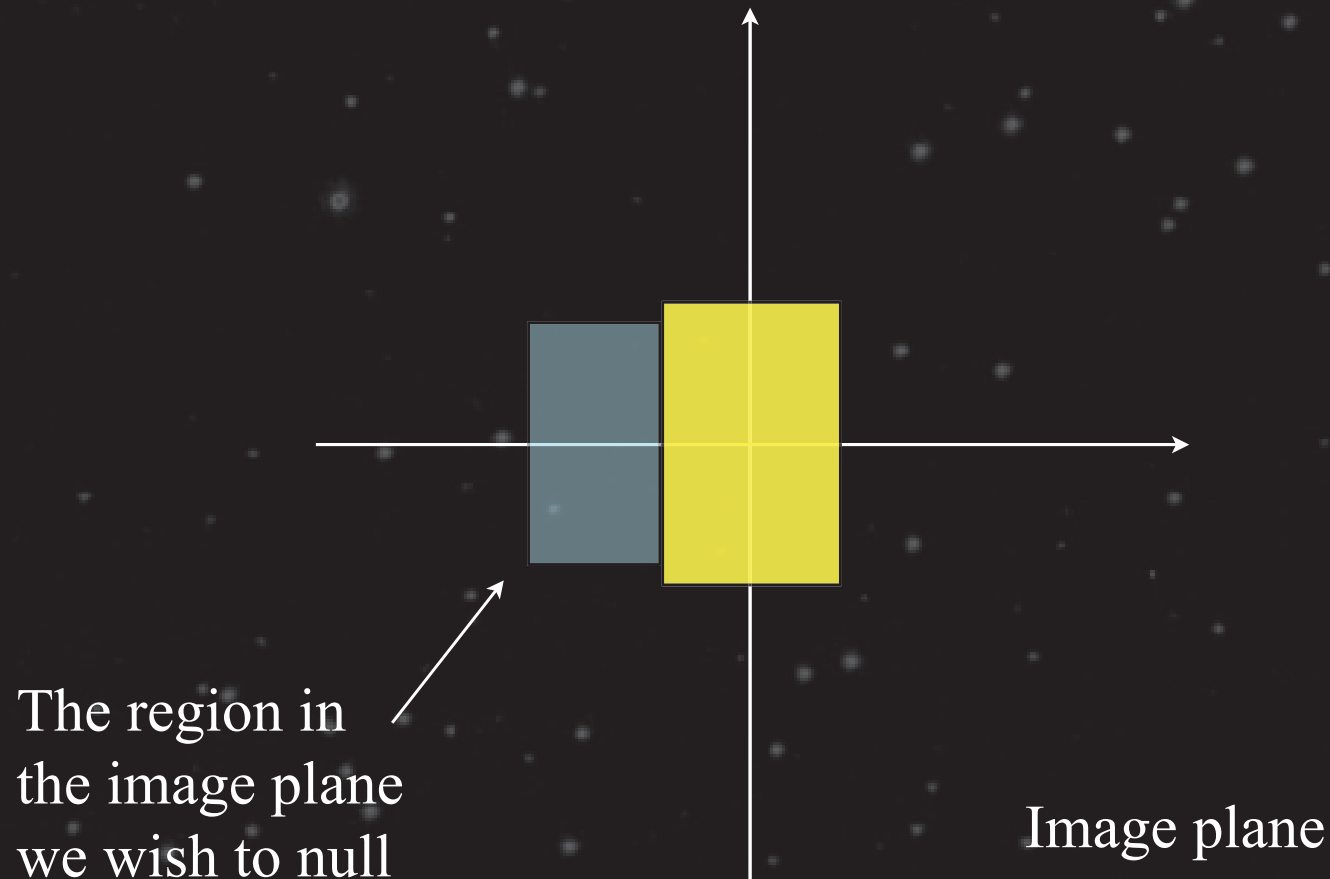
$$DM(x, y) = \text{sinc}(w_x x) \text{sinc}(w_y y)$$





What shapes on the DM should we use for the probes?

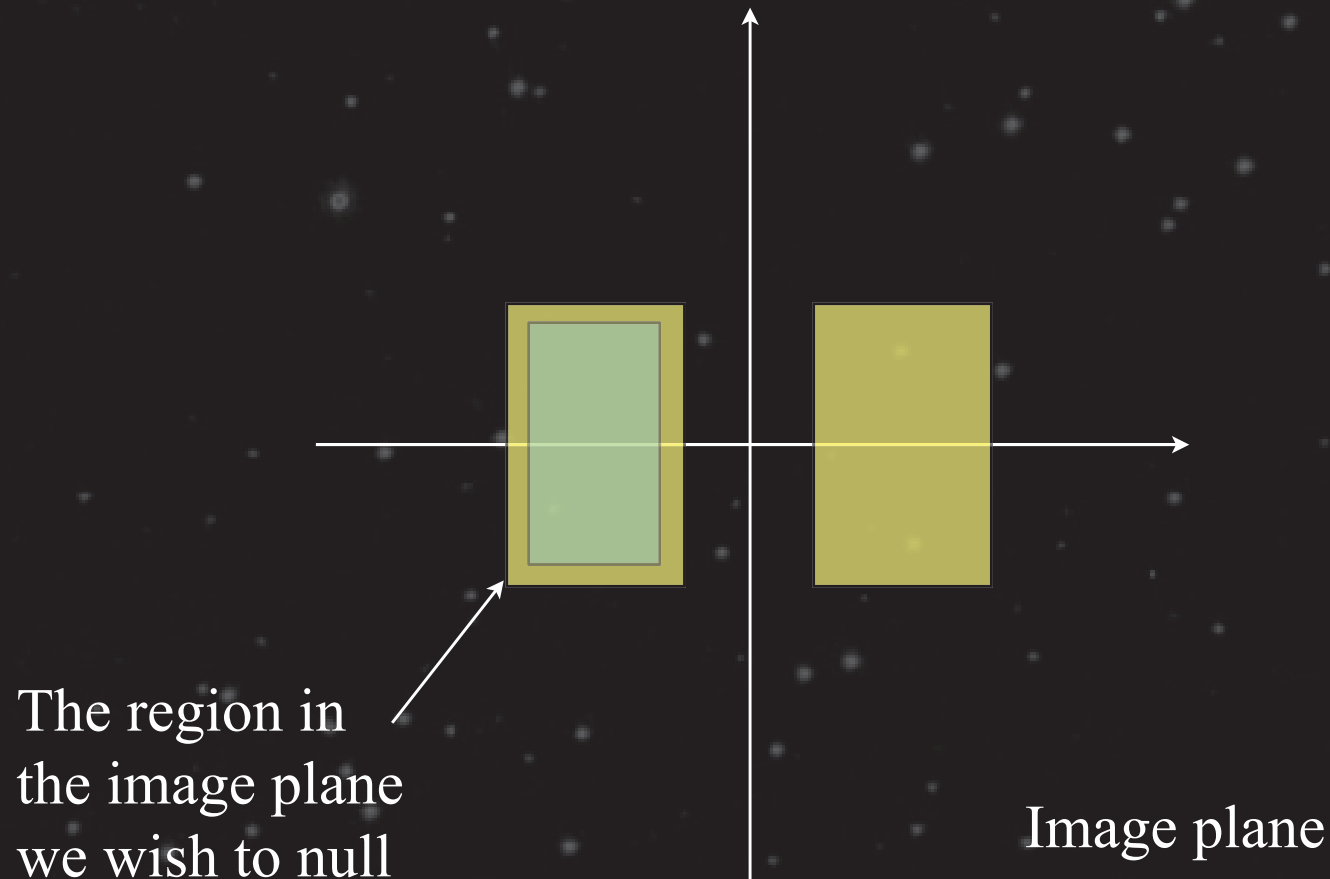
$$DM(x, y) = \text{sinc}(w_x x) \text{sinc}(w_y y) \cos(f_x x + \phi)$$





What shapes on the DM should we use for the probes?

$$DM(x, y) = \text{sinc}(w_x x) \text{sinc}(w_y y) \cos(f_x x + \phi)$$





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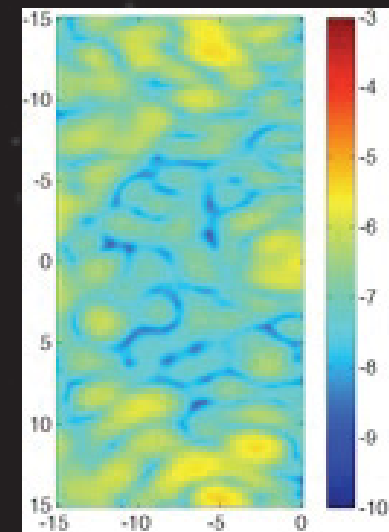


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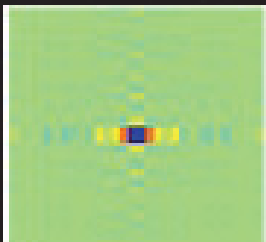
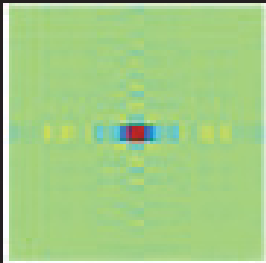
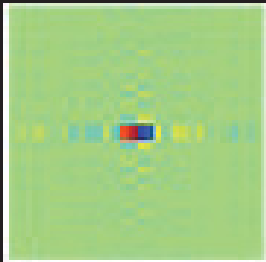
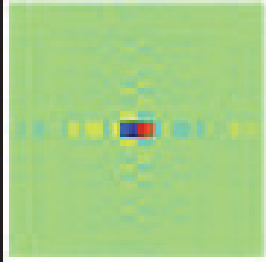
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Measured intensity

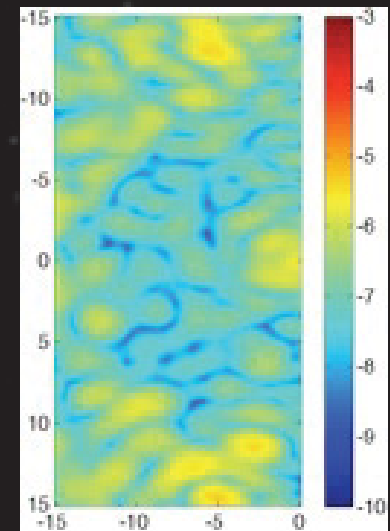


Monday, June 25, 2012

DM voltages

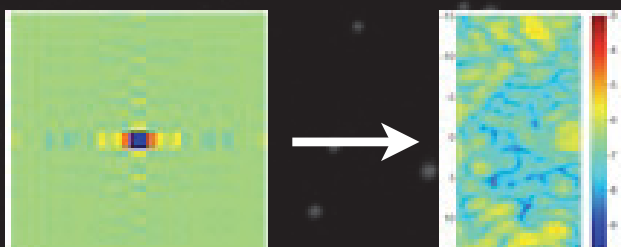
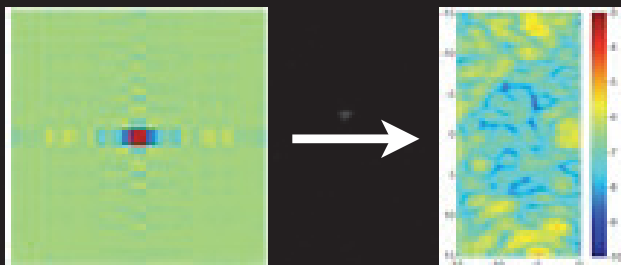
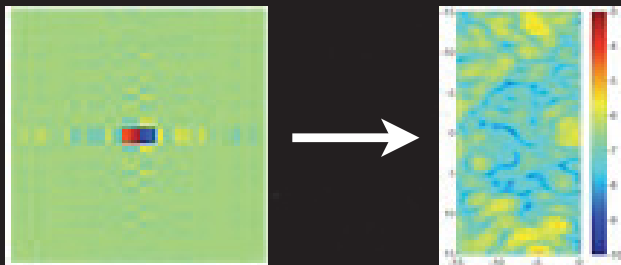
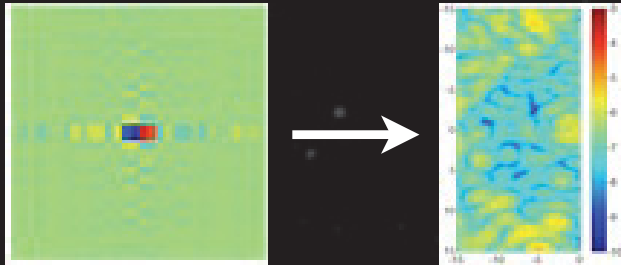


Measured intensity

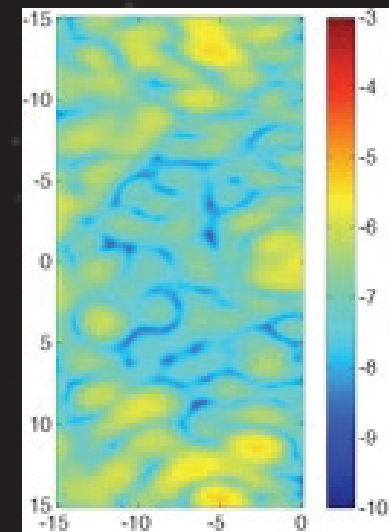


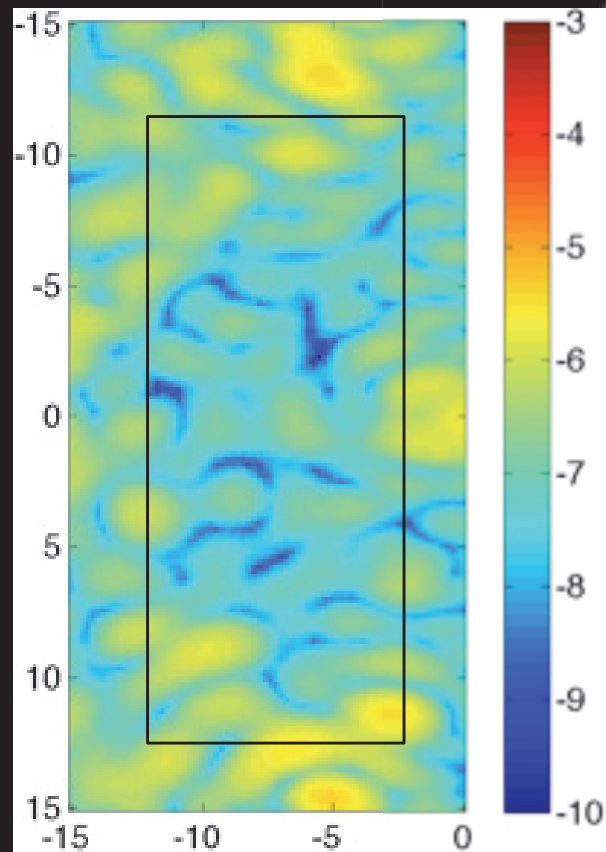
DM voltages

Probe
images

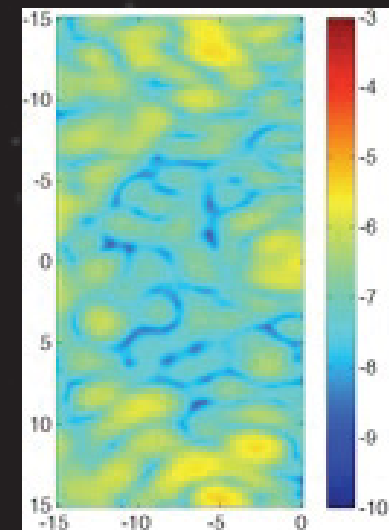


Measured intensity



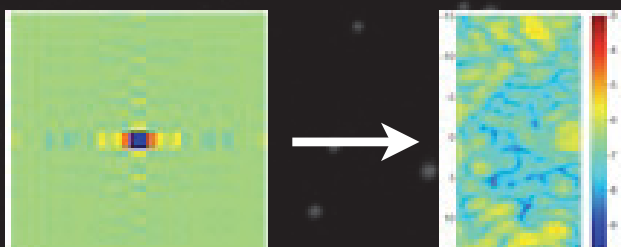
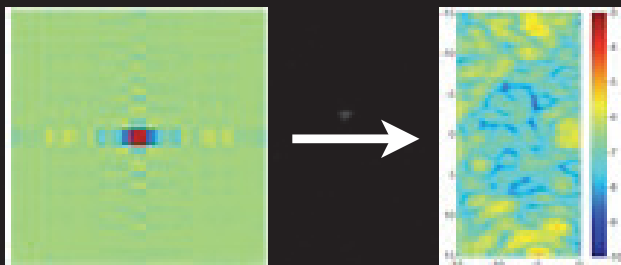
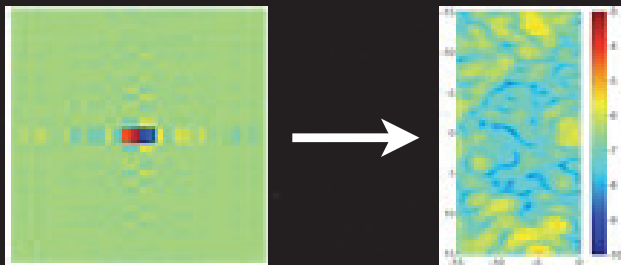
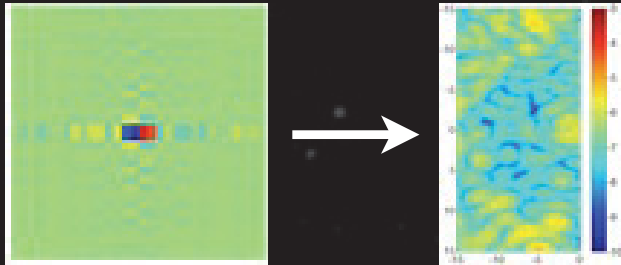


Measured intensity

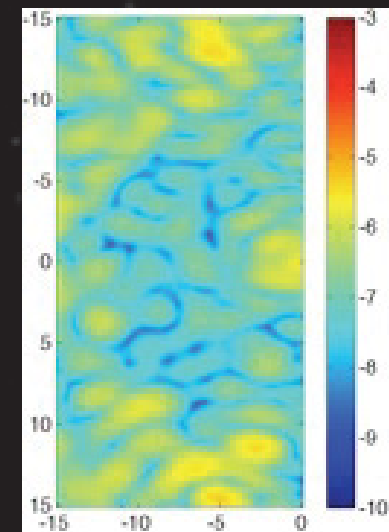


DM voltages

Probe
images



Measured intensity



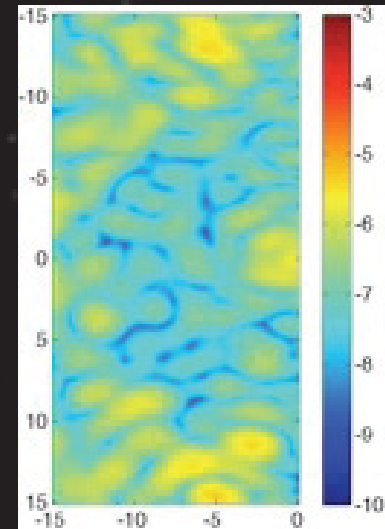
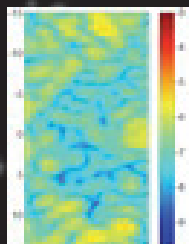
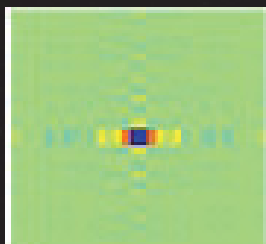
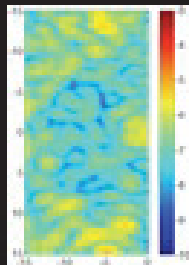
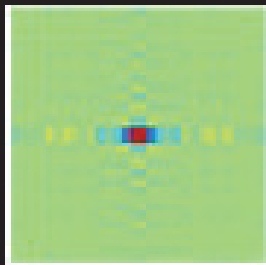
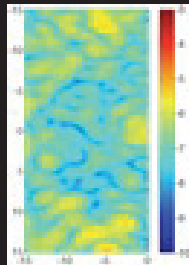
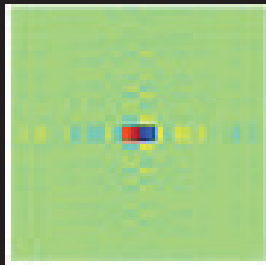
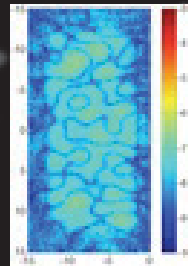
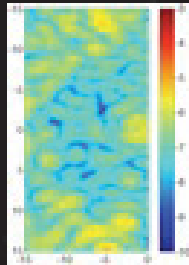
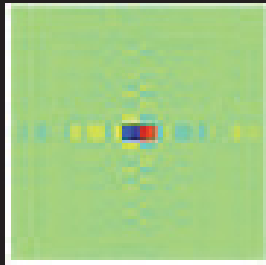


DM voltages

Probe
images

Difference

Measured intensity





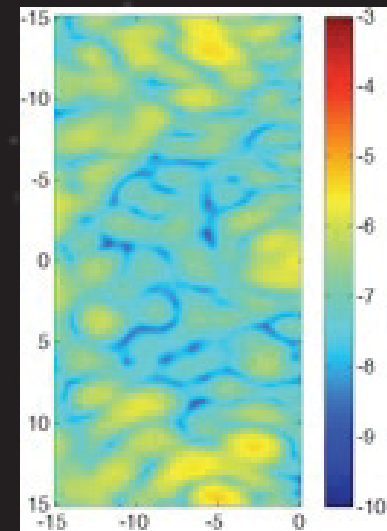
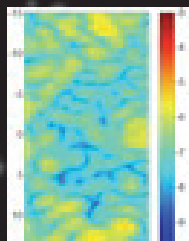
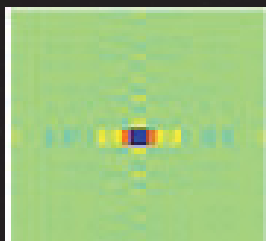
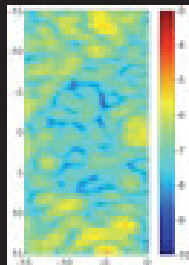
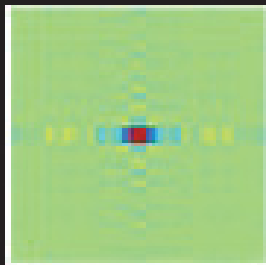
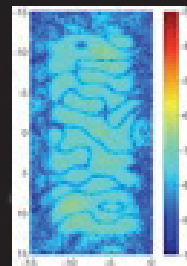
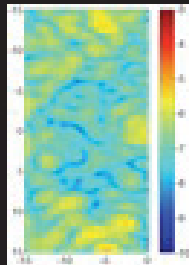
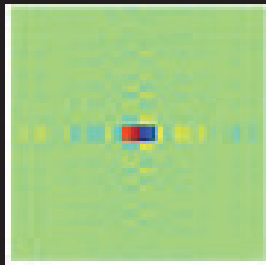
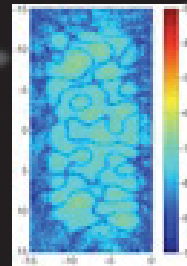
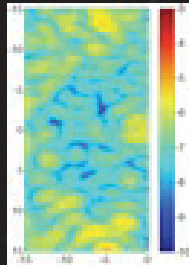
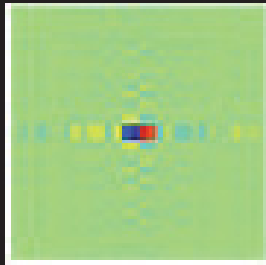
DM voltages

Probe
images

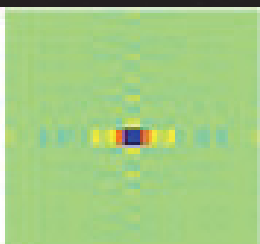
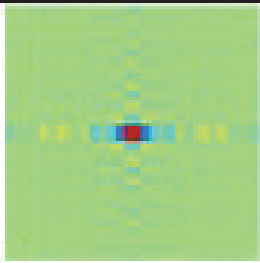
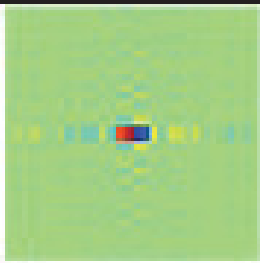
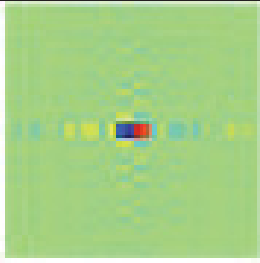
Difference

Difference

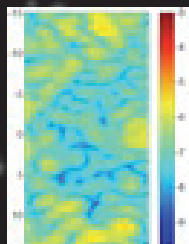
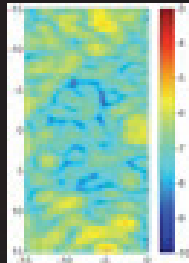
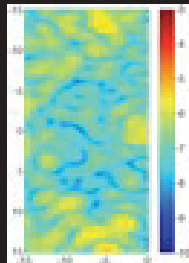
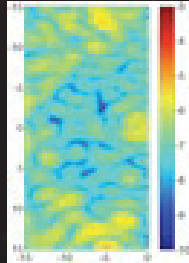
Measured intensity



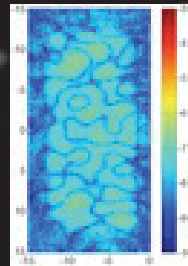
DM voltages



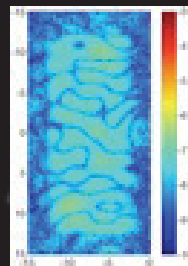
Probe
images



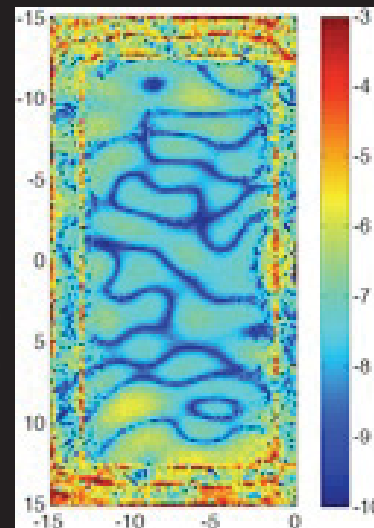
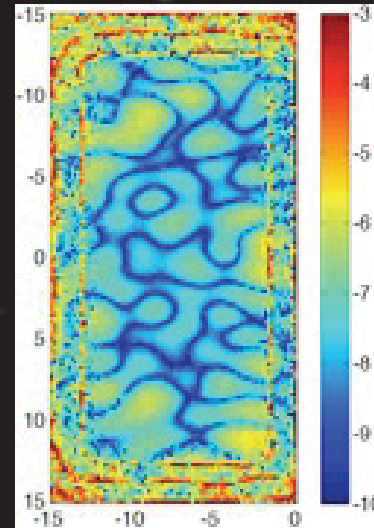
Difference



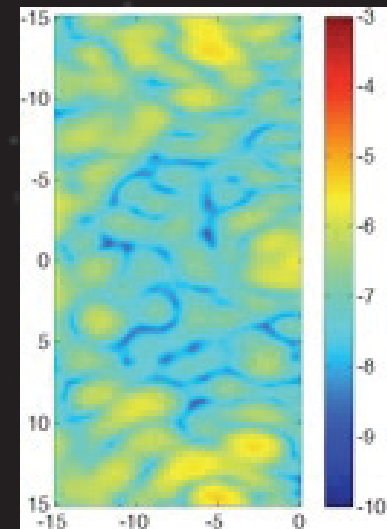
Difference



Real and imaginary
parts of the estimated
Electric field

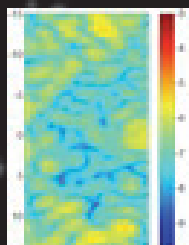
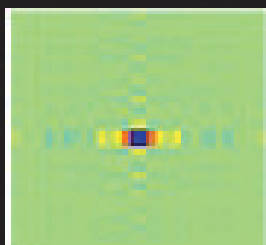
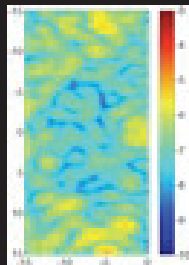
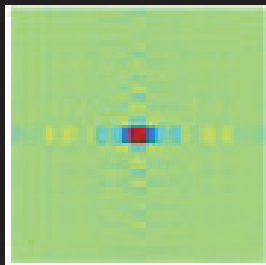
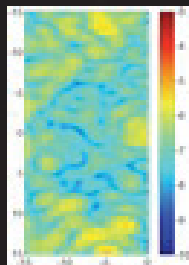
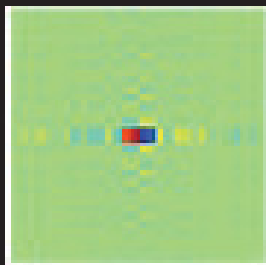
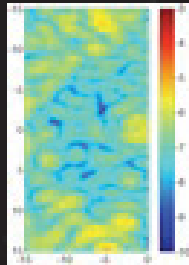
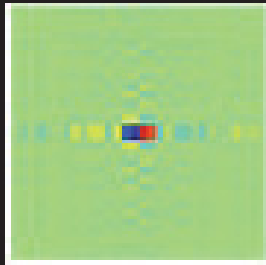


Measured intensity

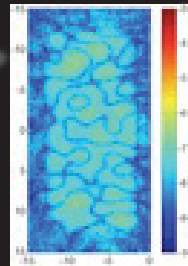


DM voltages

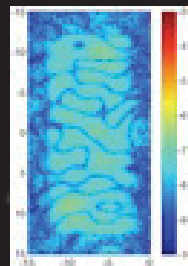
Probe
images



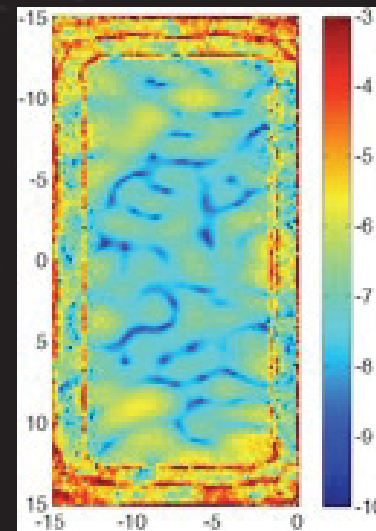
Difference



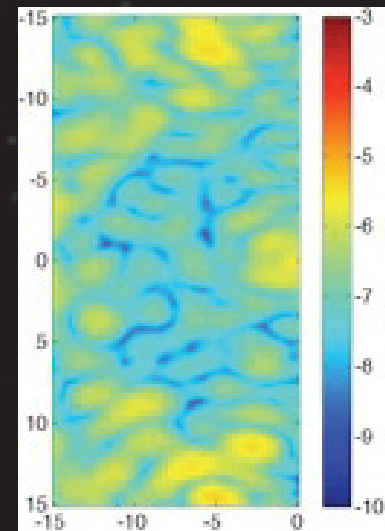
Difference

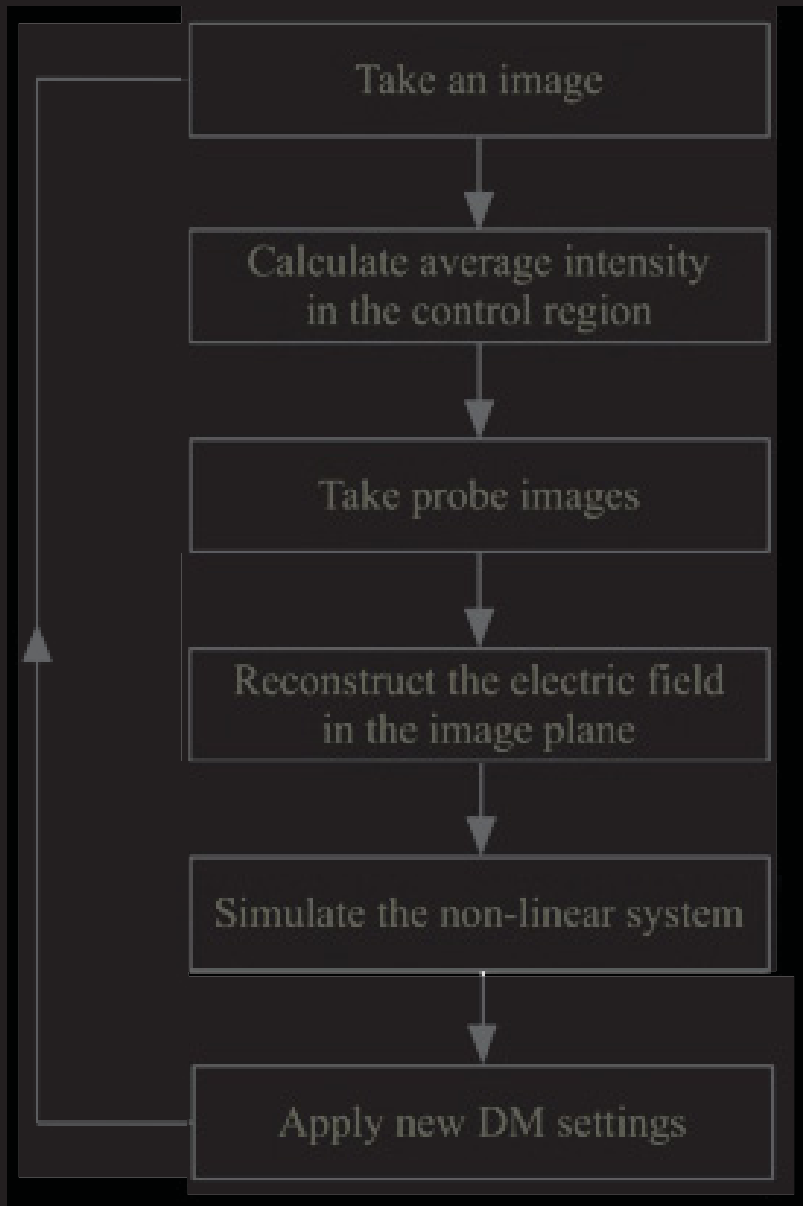


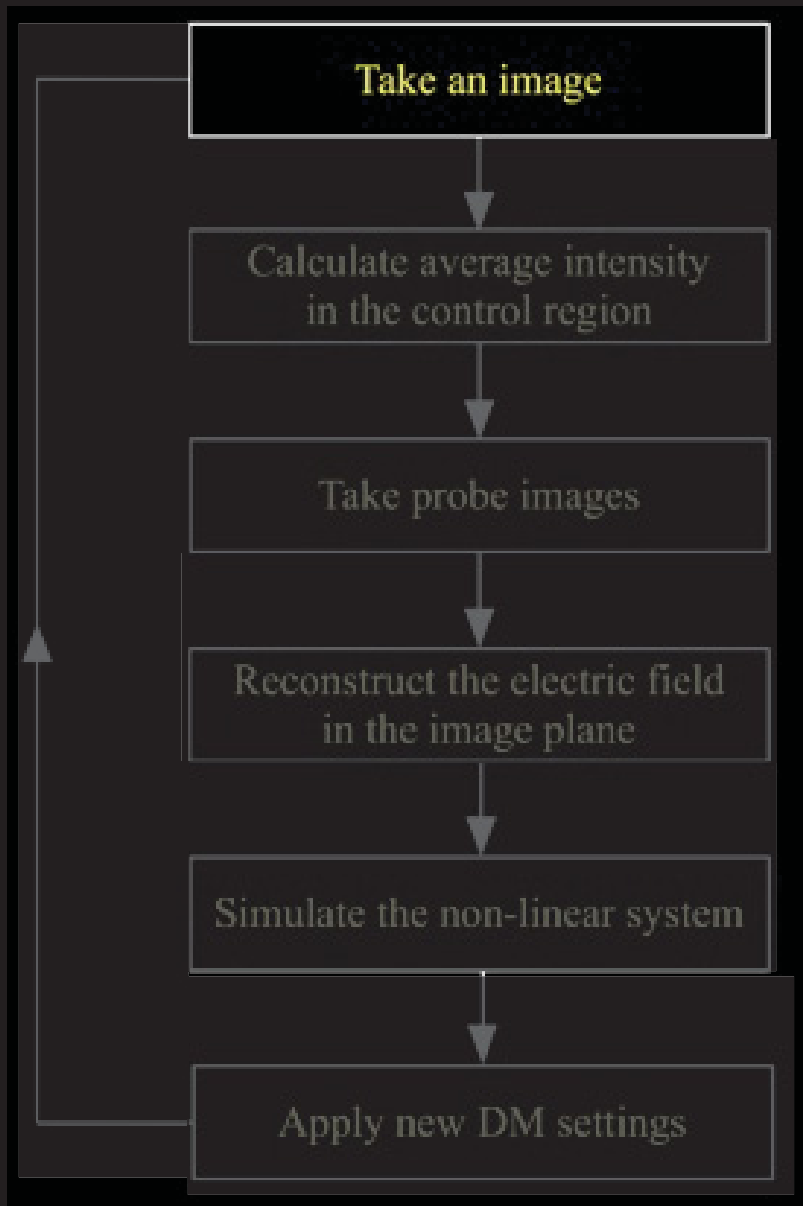
Intensity from
estimated electric field



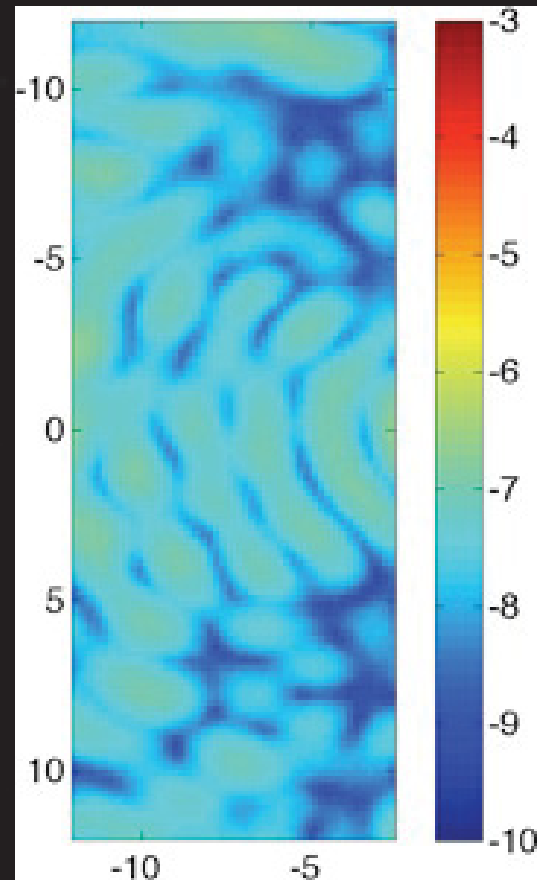
Measured intensity



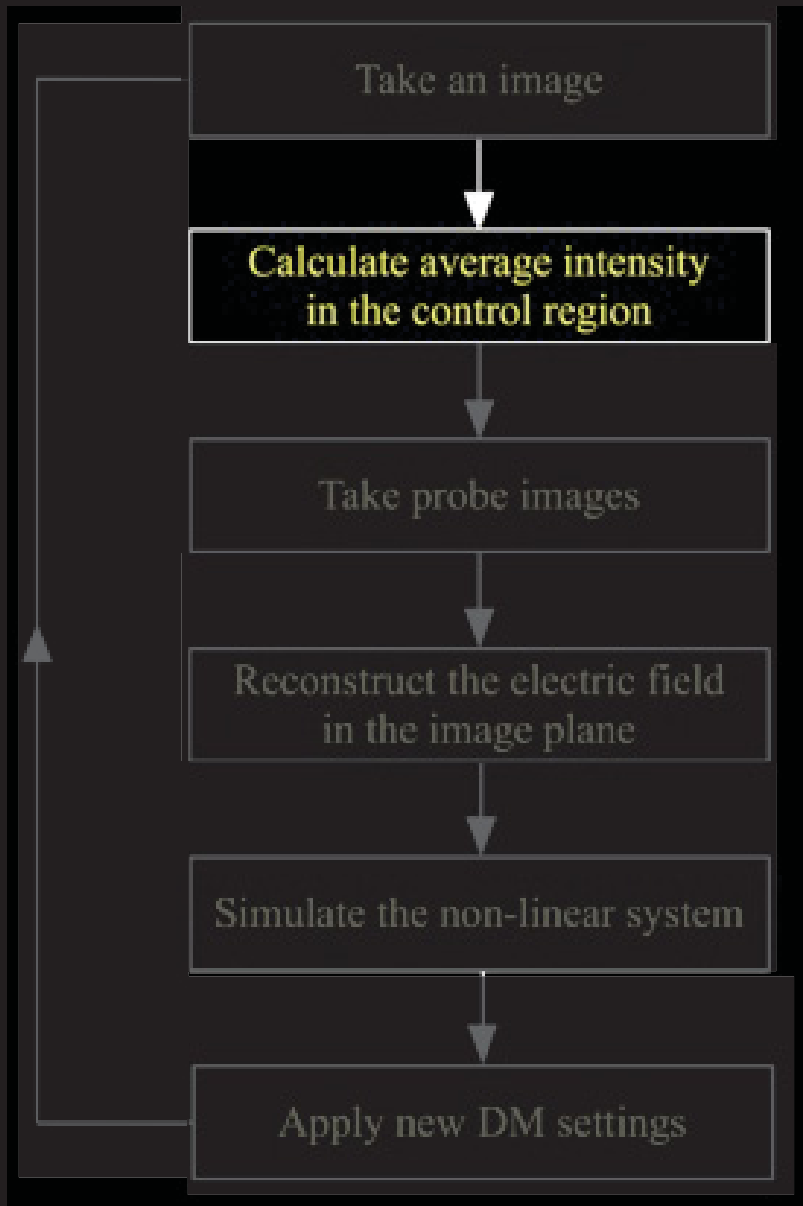




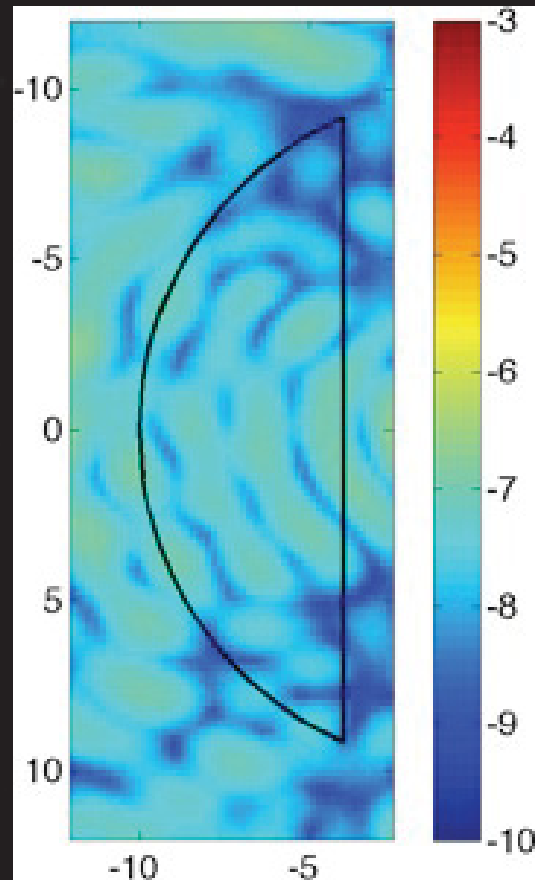
Measured
image



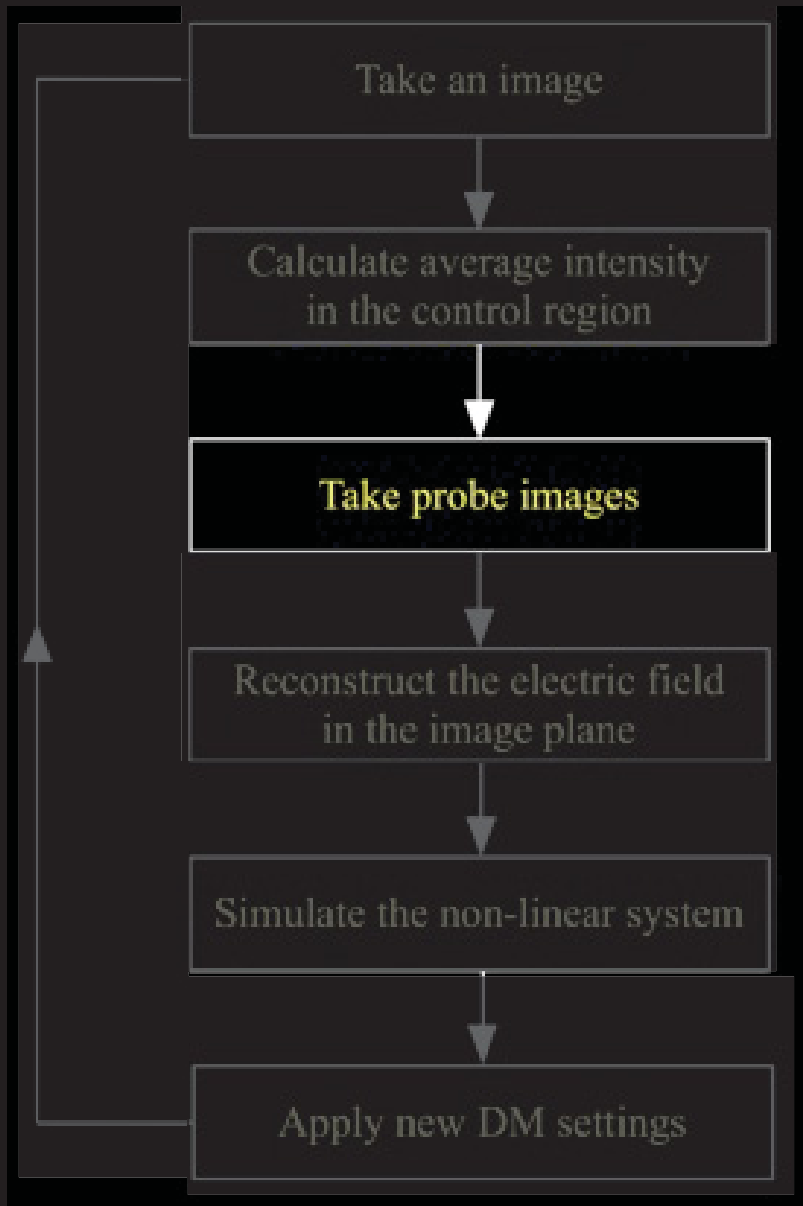
Measurements were taken at 2% around 800nm



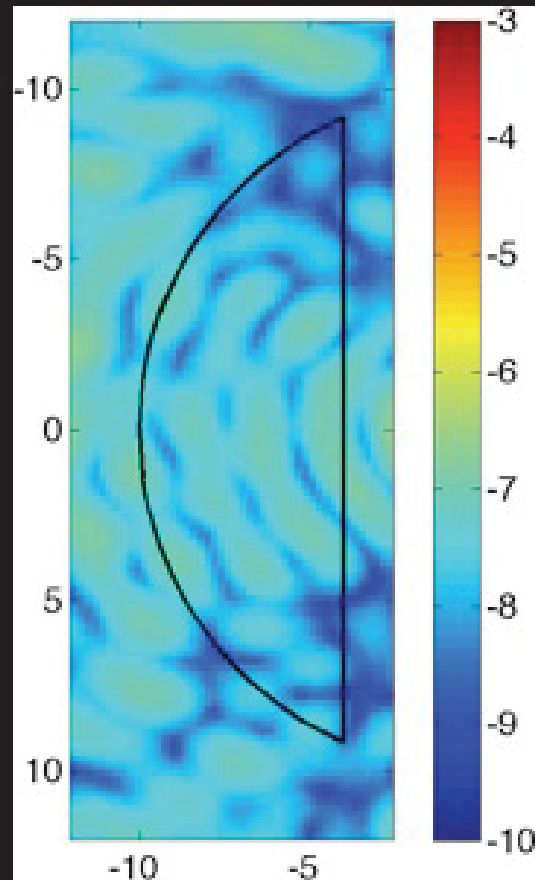
Measured
image



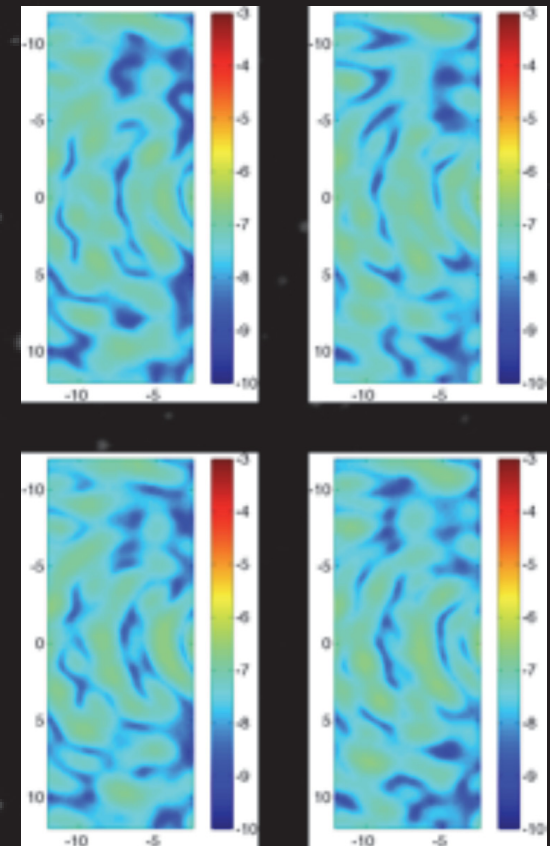
Measurements were taken at 2% around 800nm



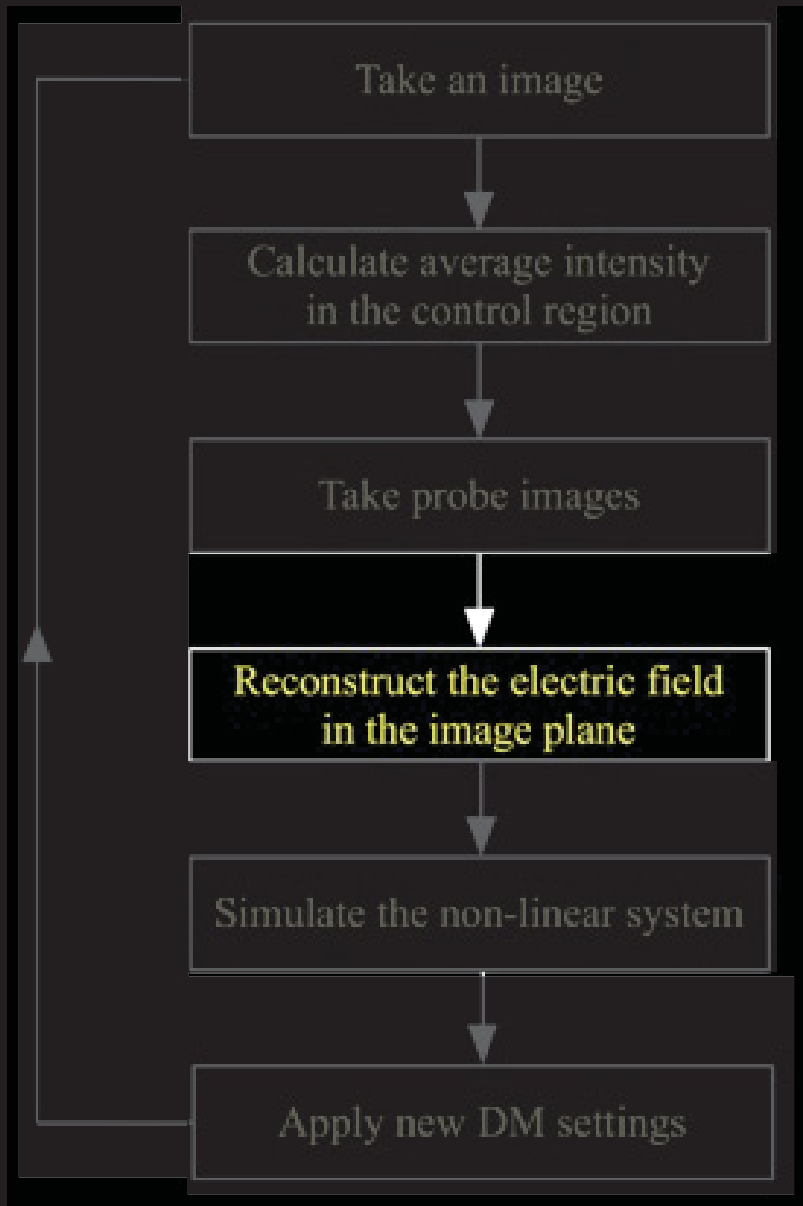
Measured
image



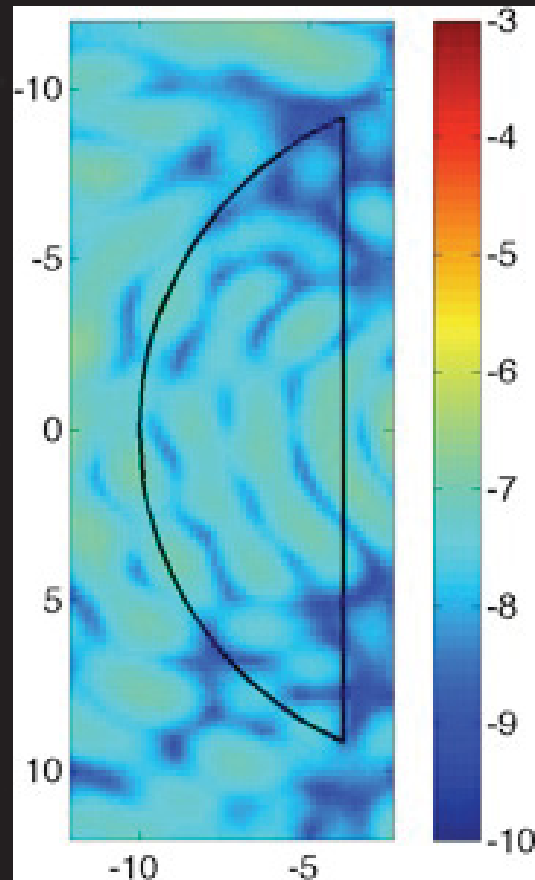
Probe images



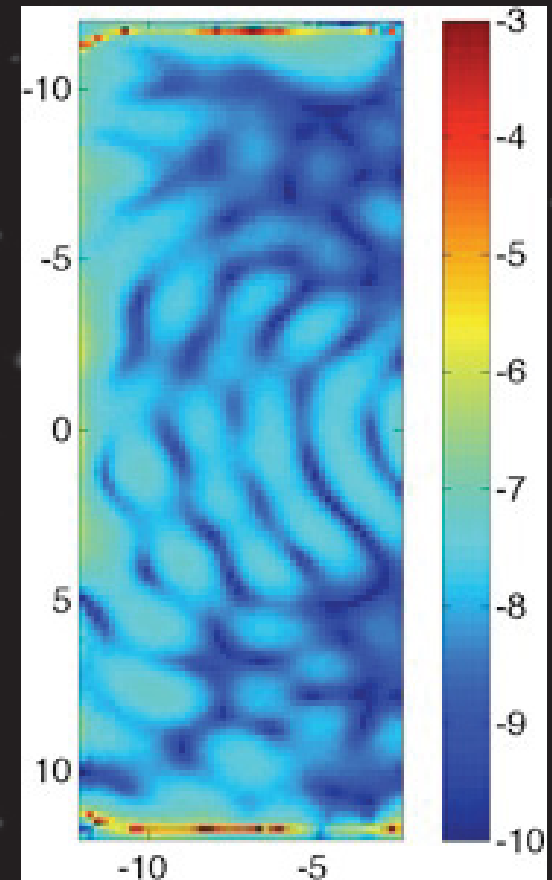
Measurements were taken at 2% around 800nm



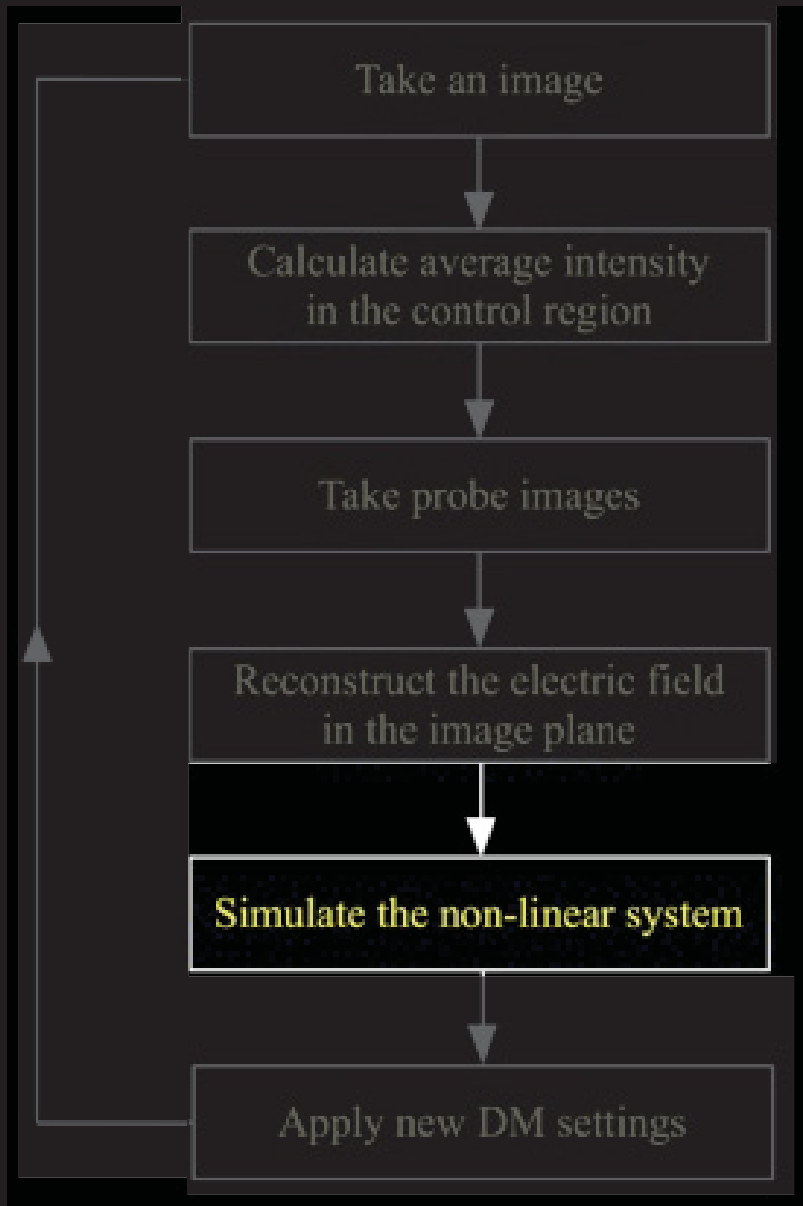
Measured
image



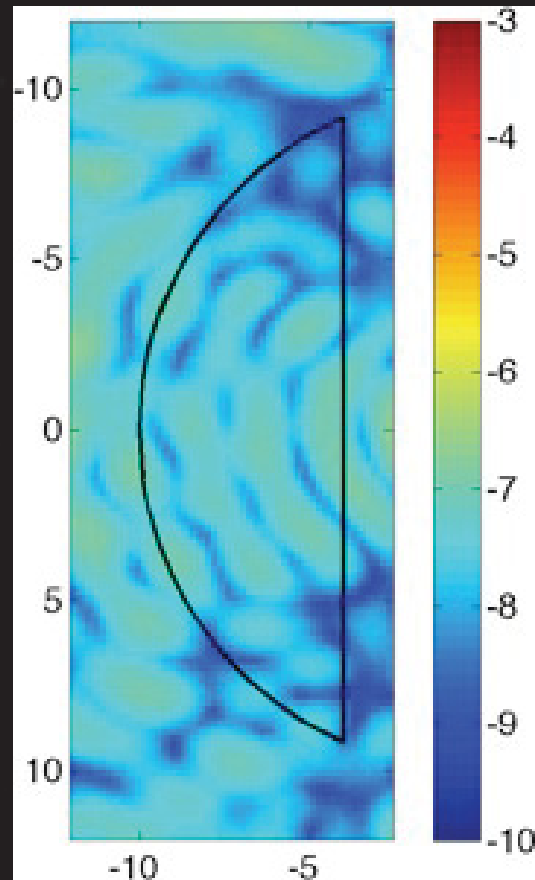
Intensity from
reconstructed
electric field



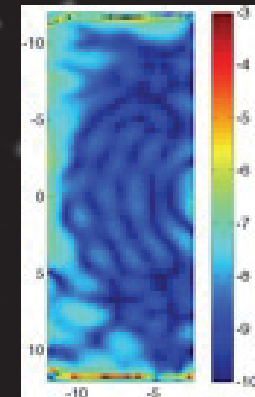
Measurements were taken at 2% around 800nm



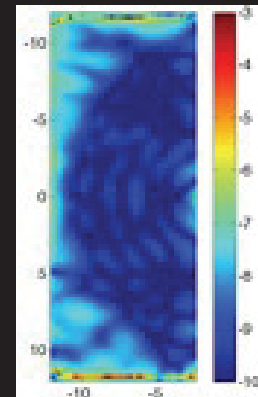
Measured
image



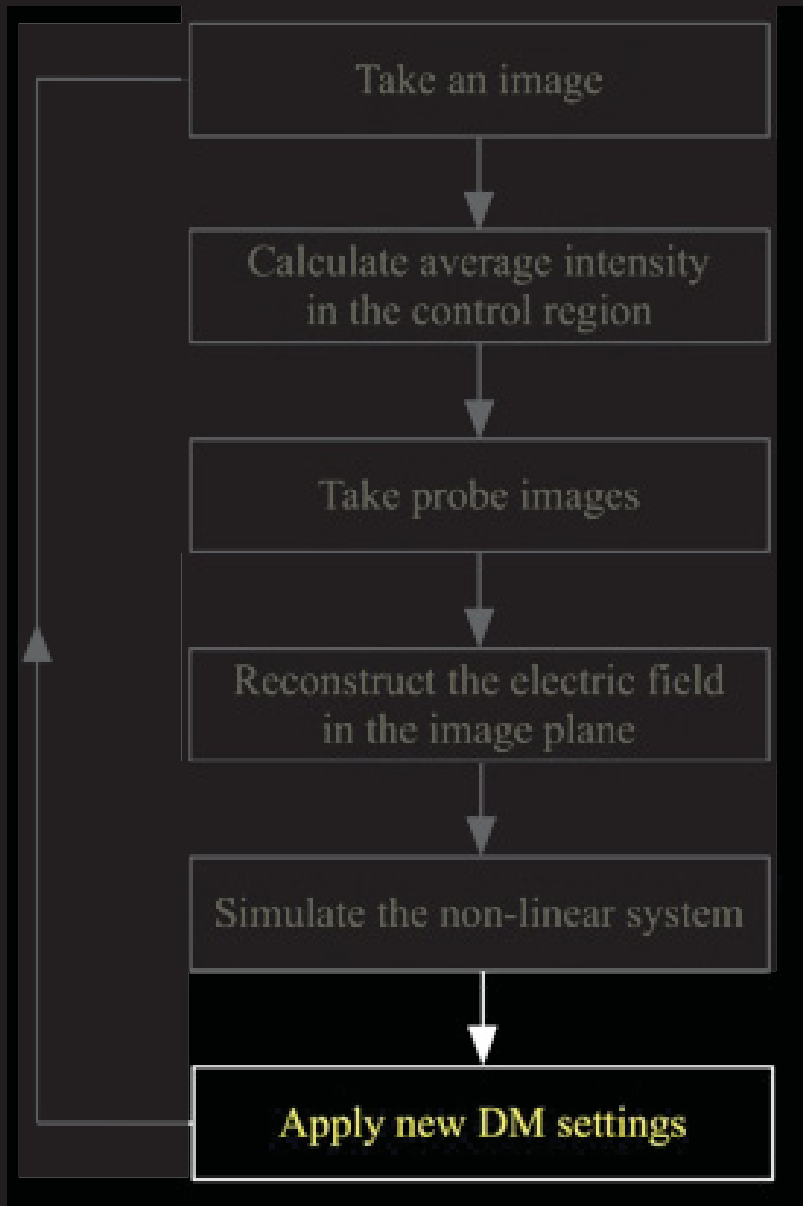
After one
iteration



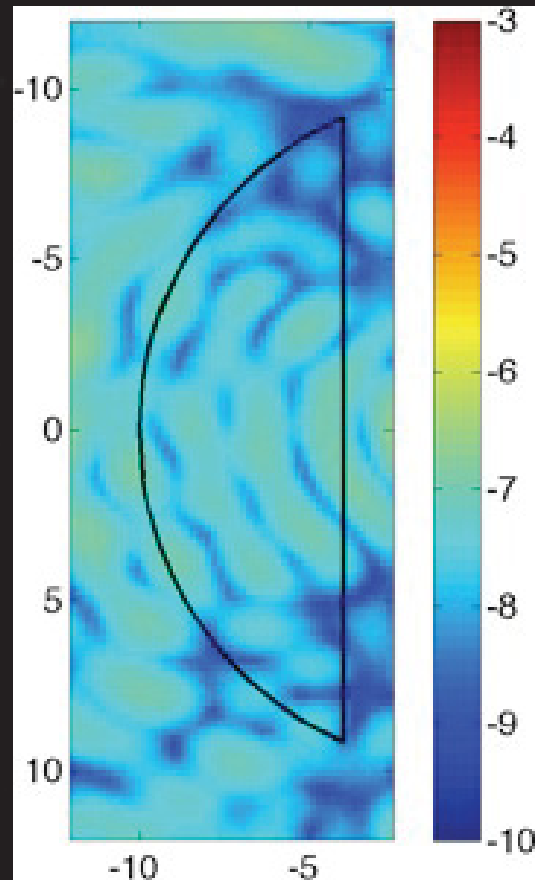
After five
non-linear
analytic
sub-steps



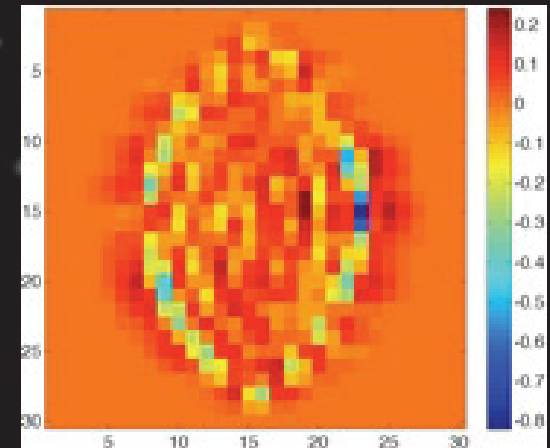
Measurements were taken at 2% around 800nm



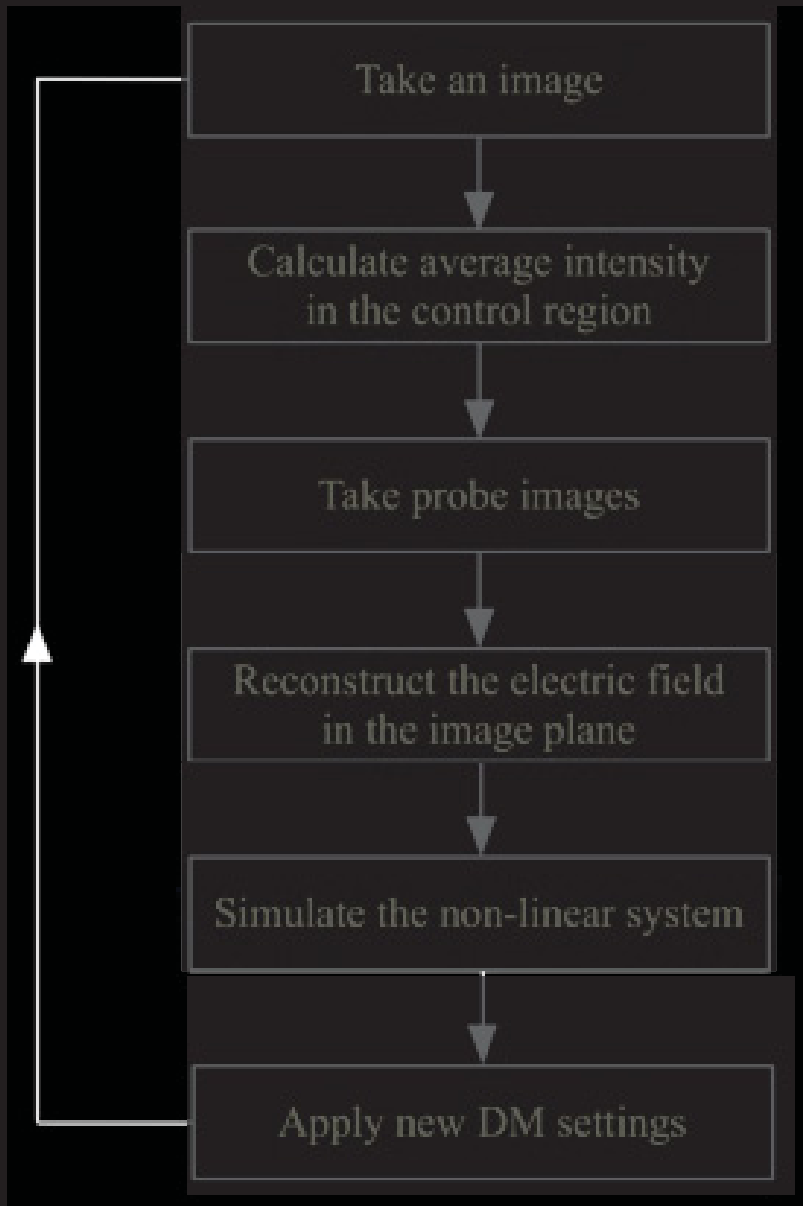
Measured
image



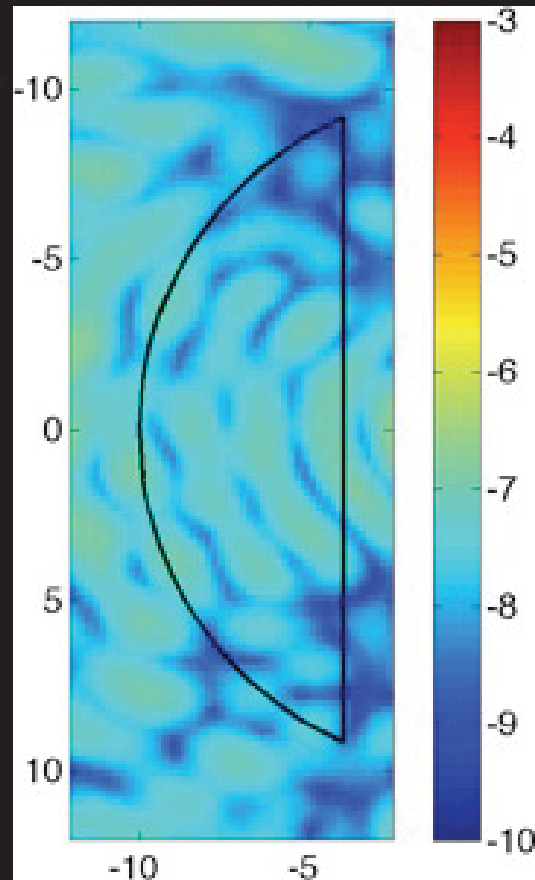
Change in
DM actuators



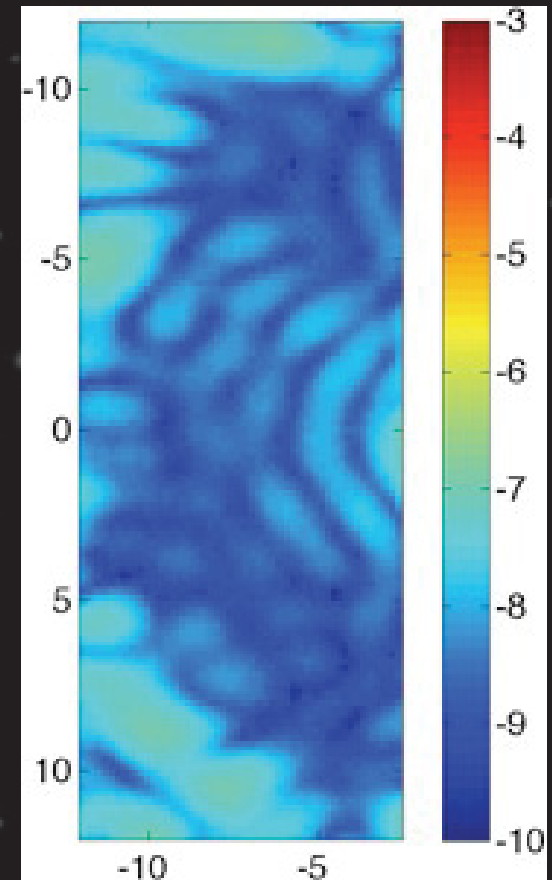
Measurements were taken at 2% around 800nm



Measured
image



New measured
image

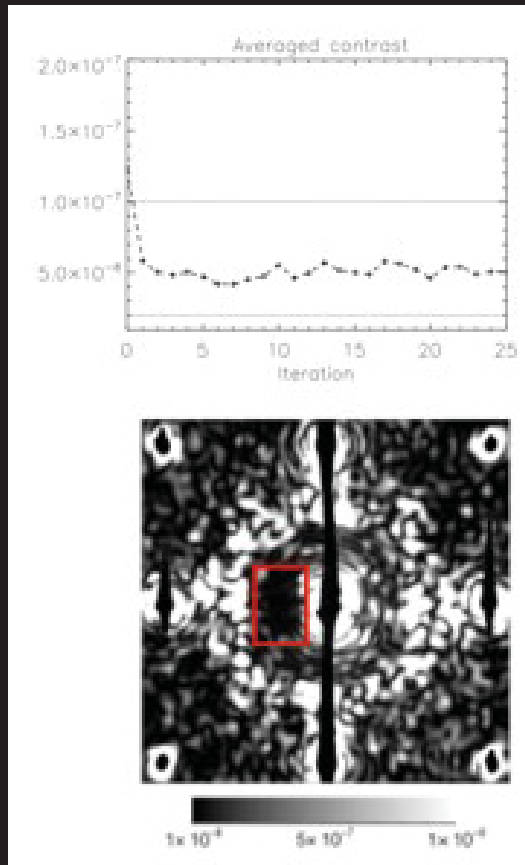


Measurements were taken at 2% around 800nm



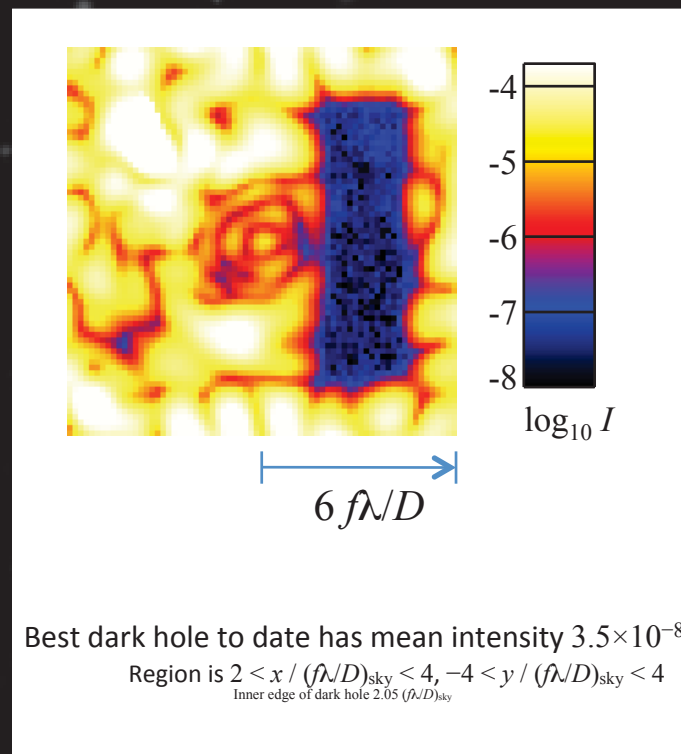
Results in various labs

Laboratory for Adaptive Optics UC Santa-Cruz

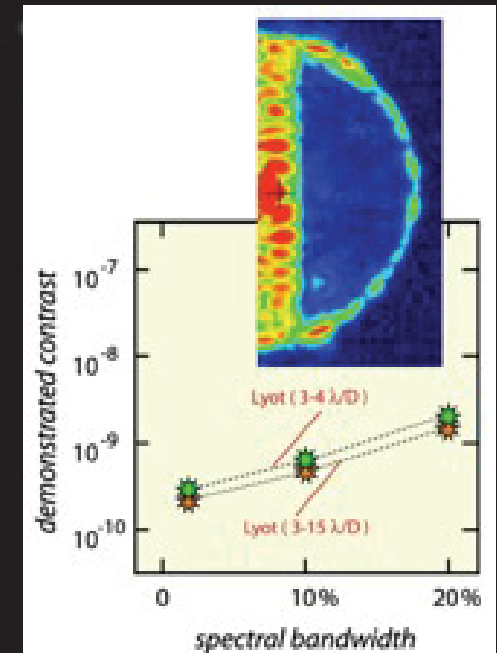


Give'on et al 2008, Thomas et al 2010

High Contrast Imaging Testbed Jet Propulsion Laboratory



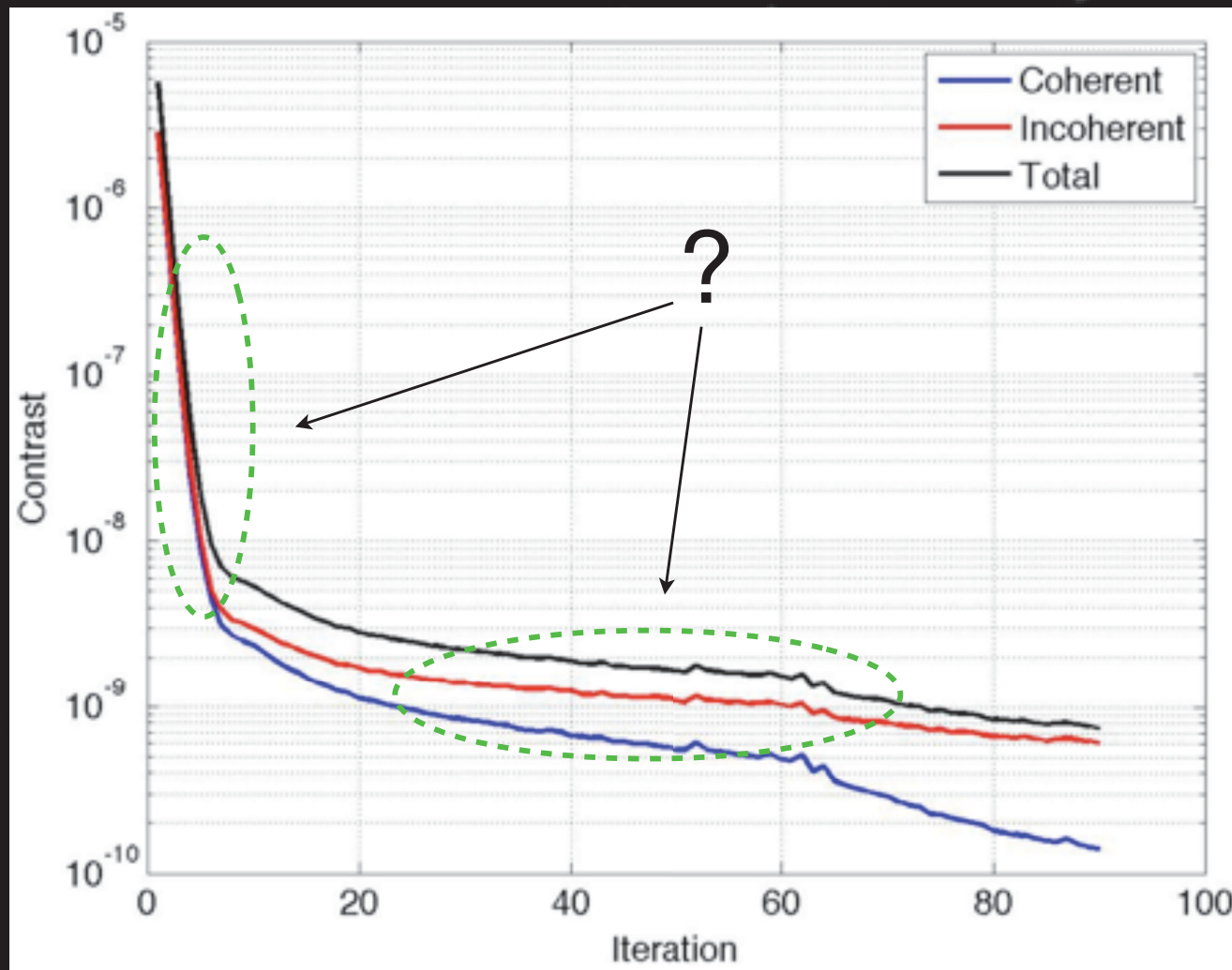
Kern et al SPIE 8151, 2011



Trauger et al SPIE 8151, 2011



Incoherent? or Uncontrollable? or?...



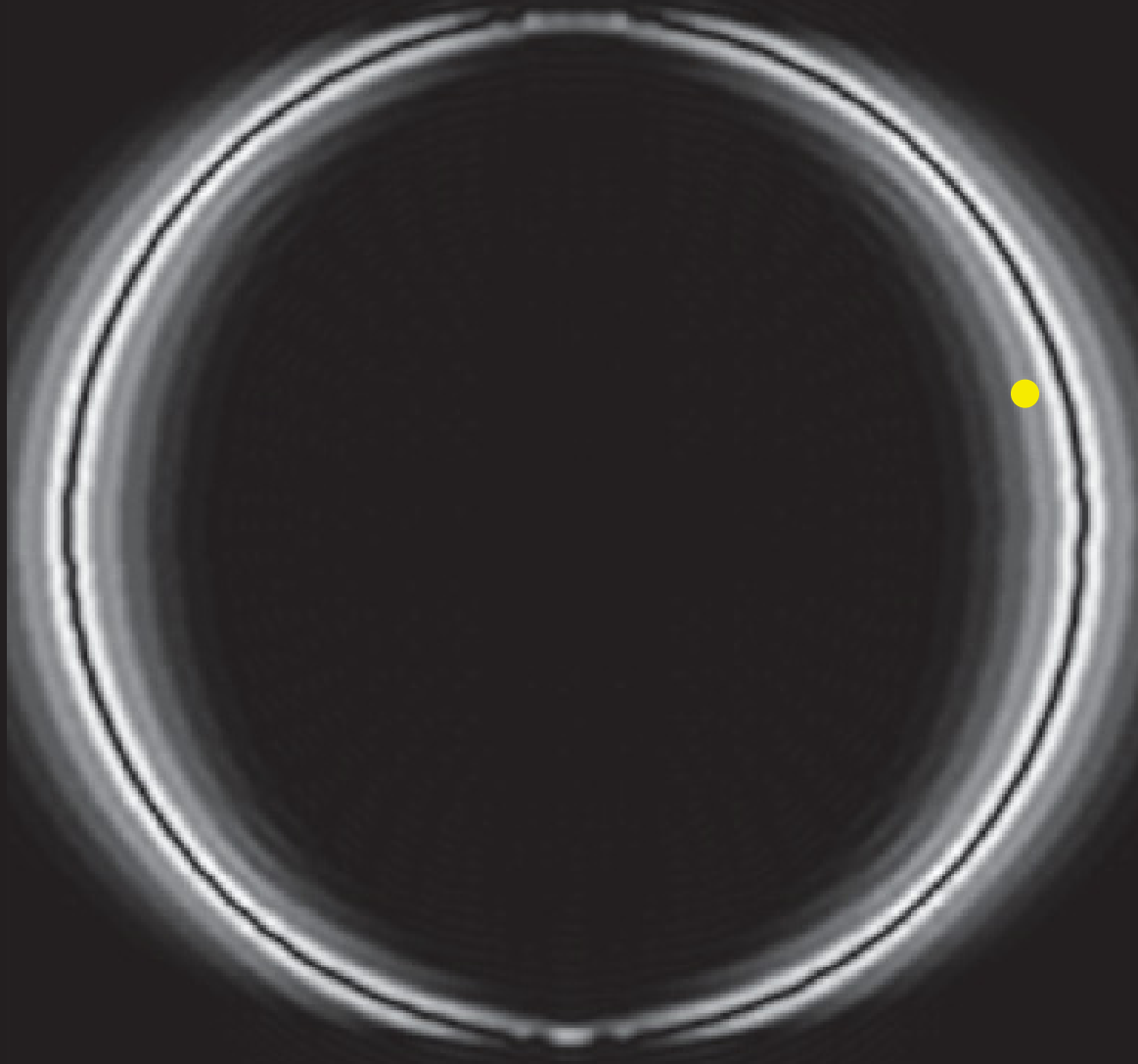
This can be due to inability to resolve changes over time, space or polarization (in between exposures of the probes).

However, this can also be due to errors in the model of the system (probes).



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Light in the Lyot plane

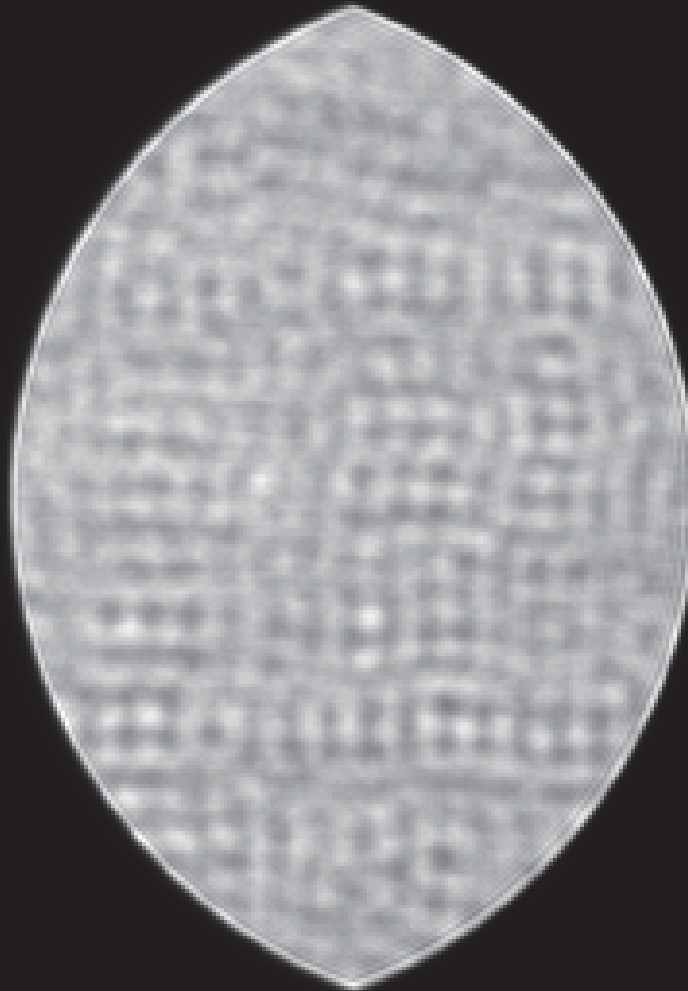


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The Peek-a-Boo estimation method

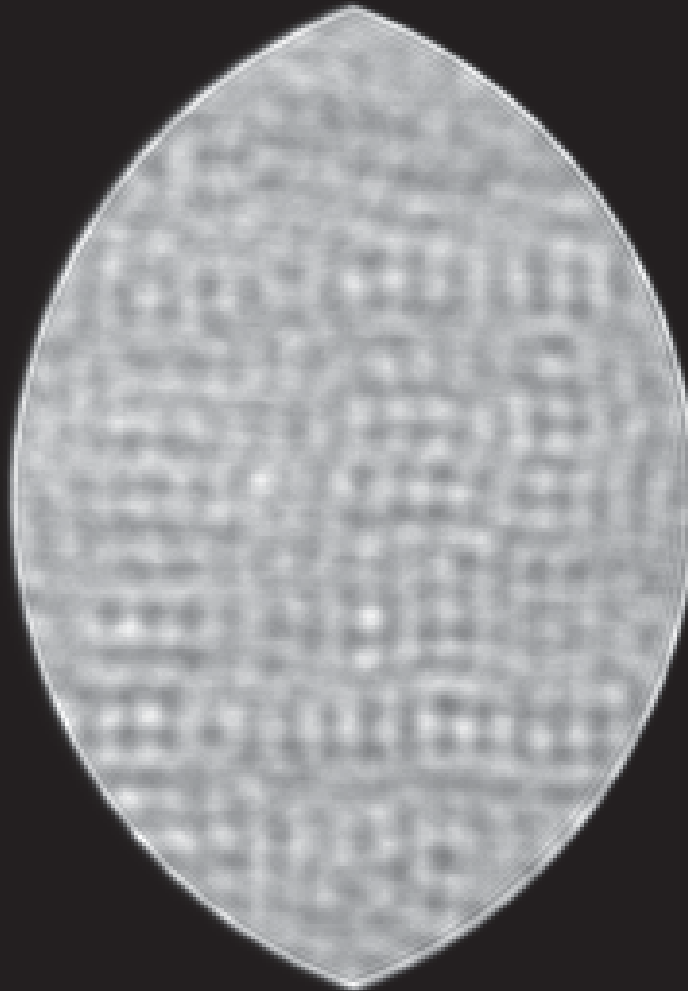
Rather than changing the DM, we let light through a pinhole at a different location each time





The Peek-a-Boo estimation method

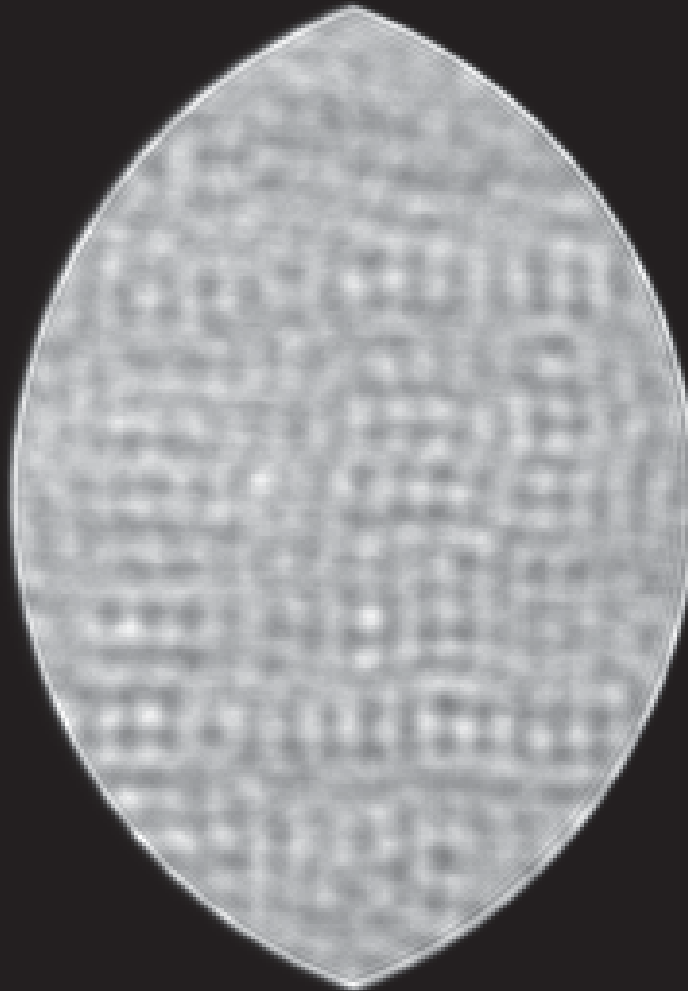
Rather than changing the DM, we let light through a pinhole at a different location each time





The Peek-a-Boo estimation method

Rather than changing the DM, we let light through a pinhole at a different location each time

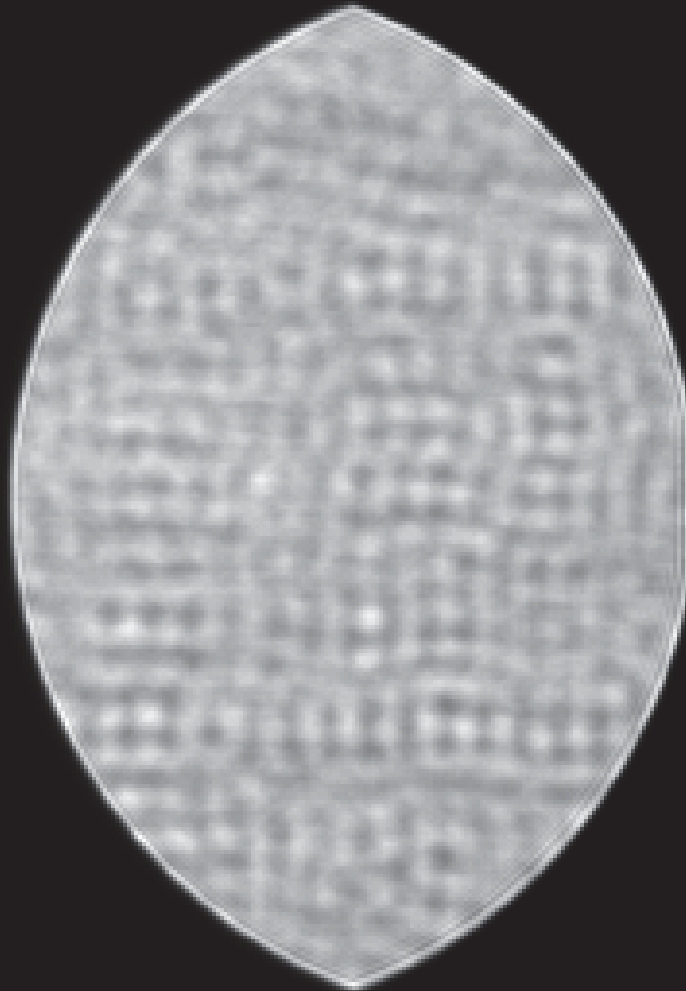


+



The Peek-a-Boo estimation method

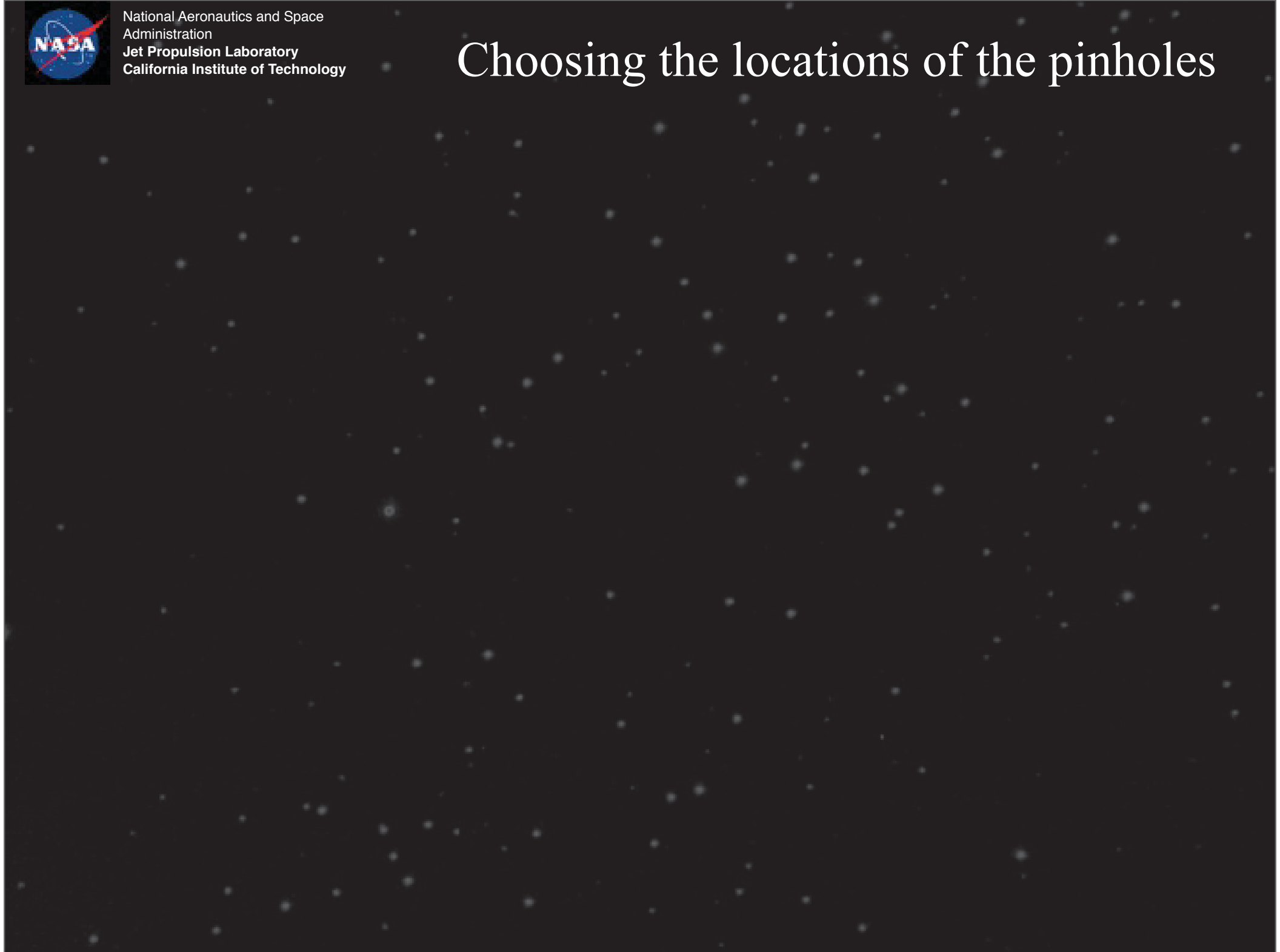
Rather than changing the DM, we let light through a pinhole at a different location each time





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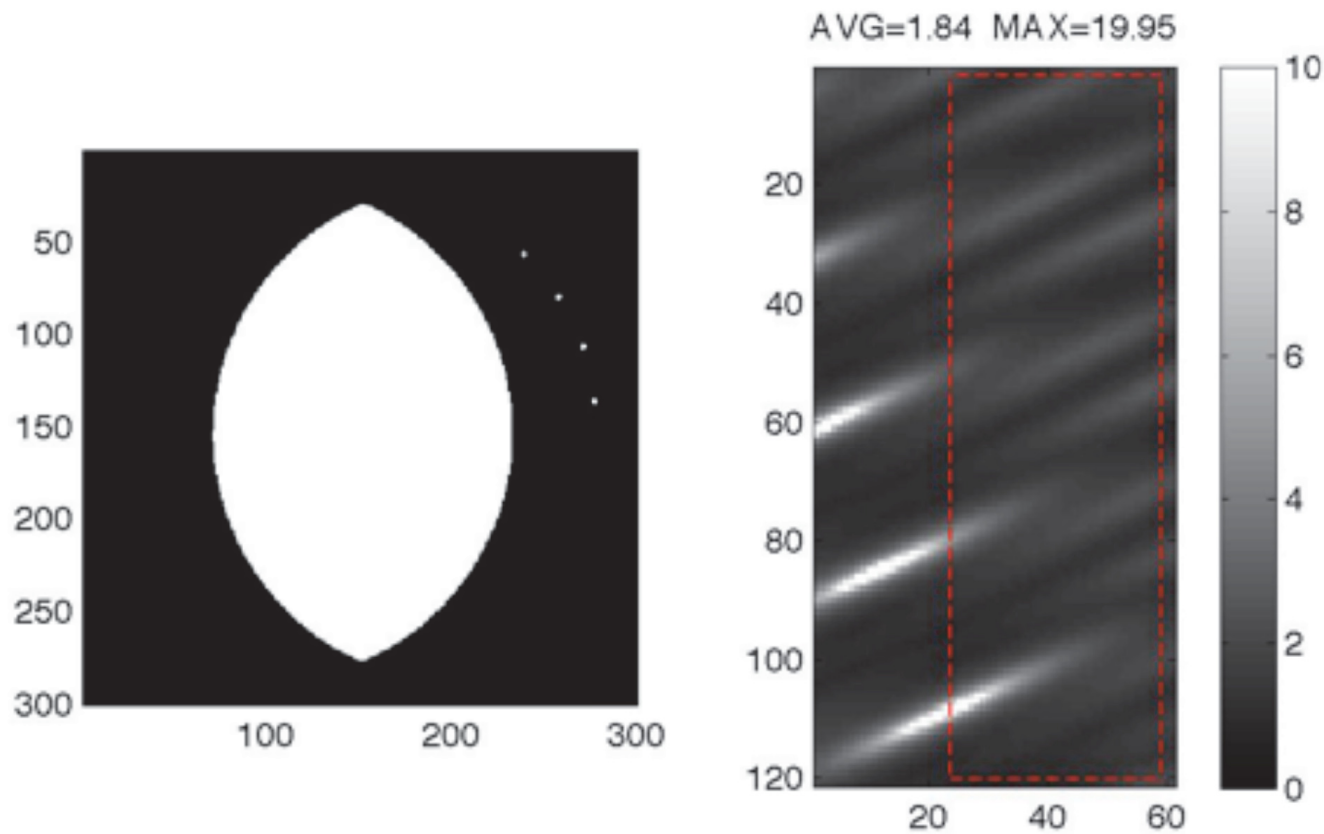
Choosing the locations of the pinholes



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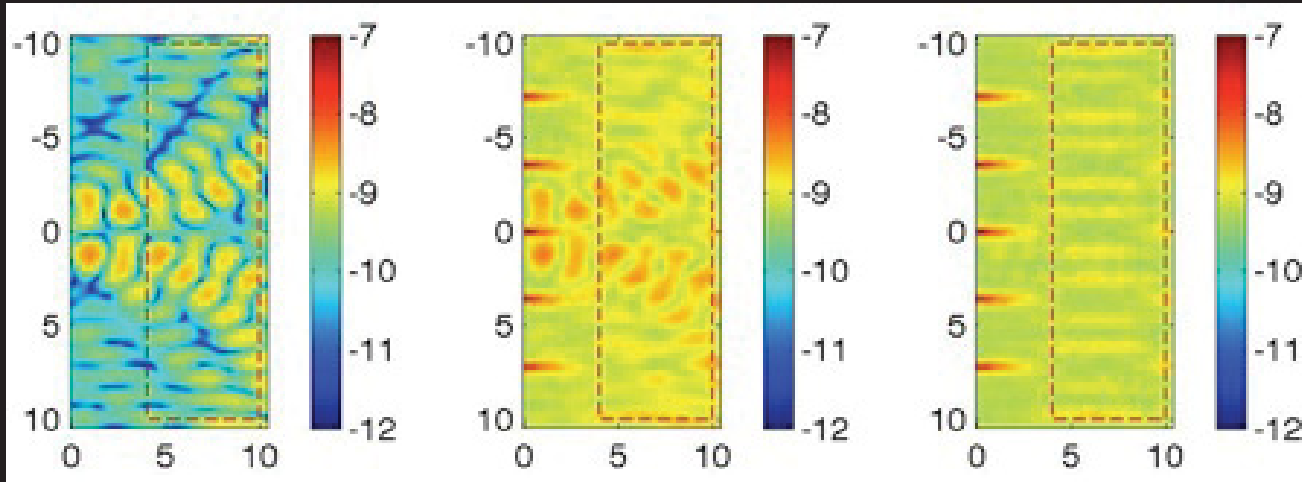


Choosing the locations of the pinholes

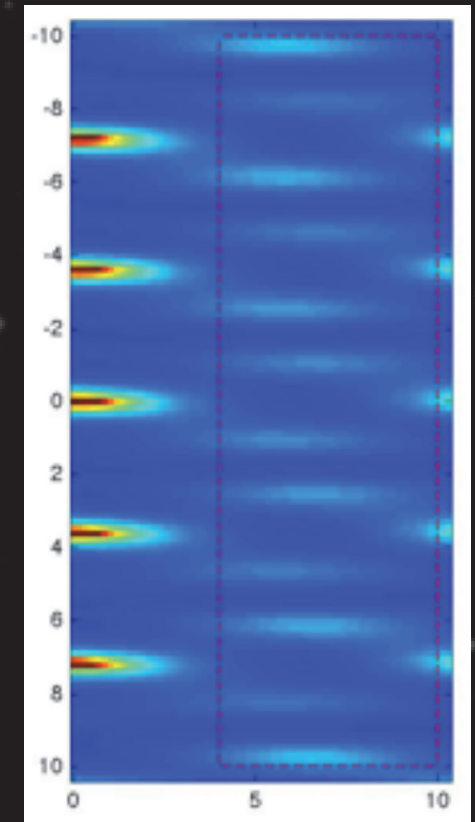
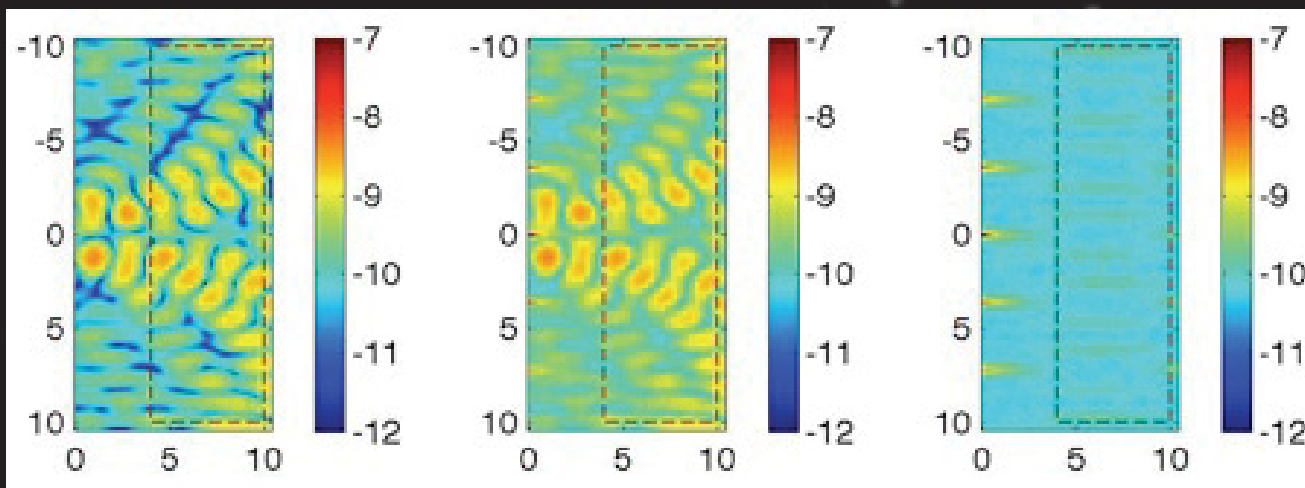


Simulations with photon noise

1 Photon per $1e-8$ contrast



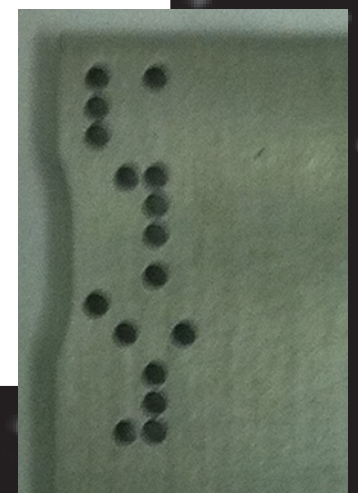
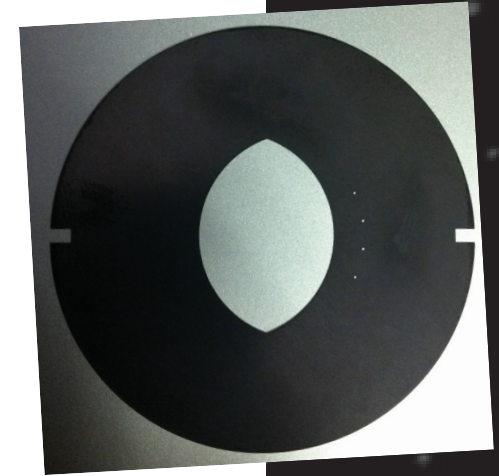
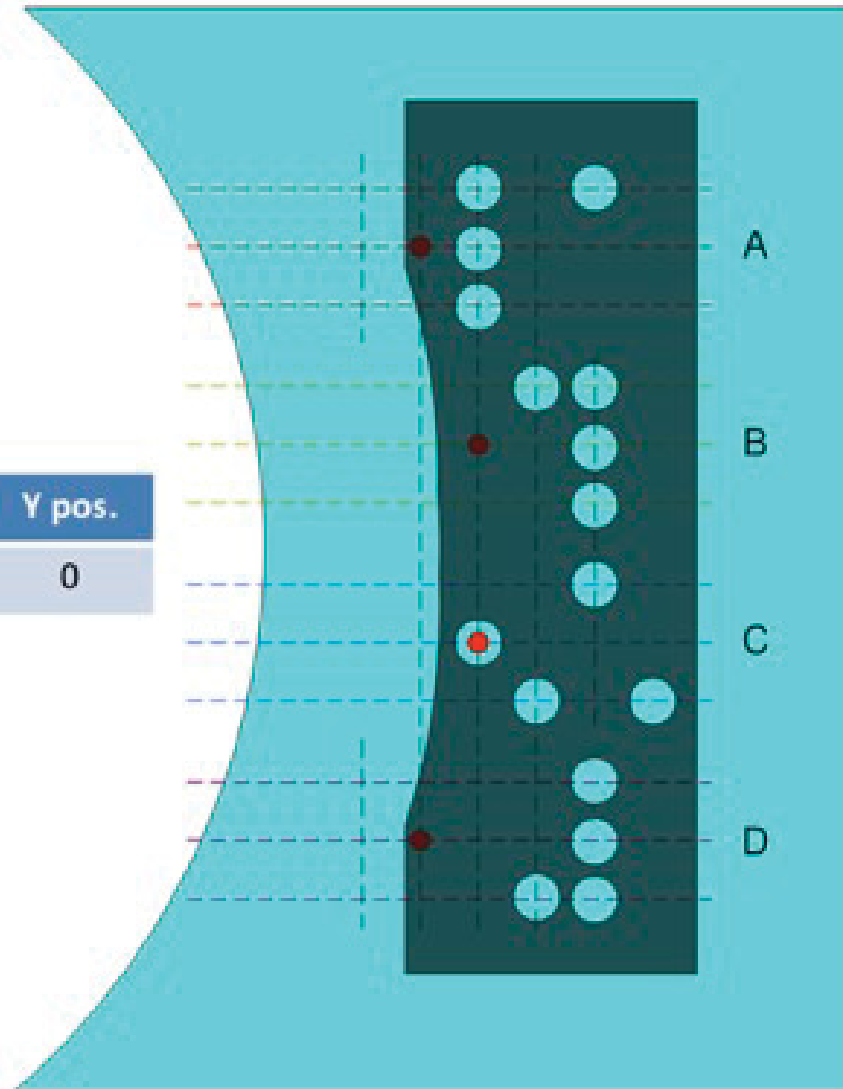
1 Photon per $1e-9$ contrast





Selecting the pinholes

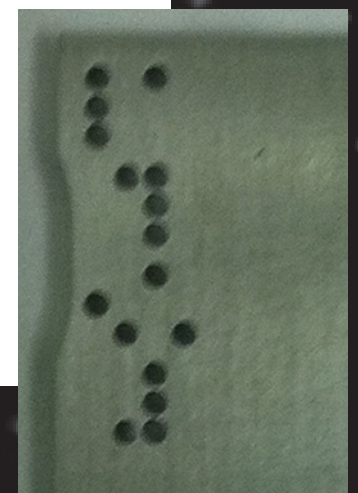
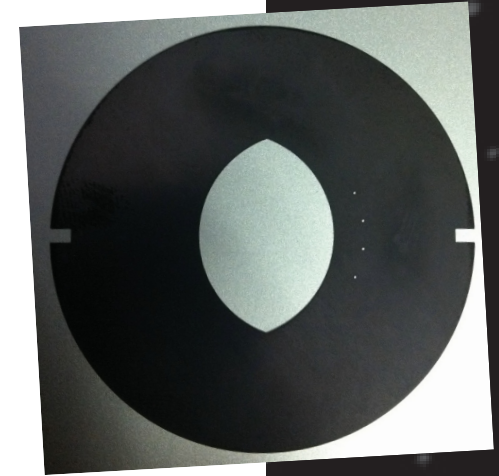
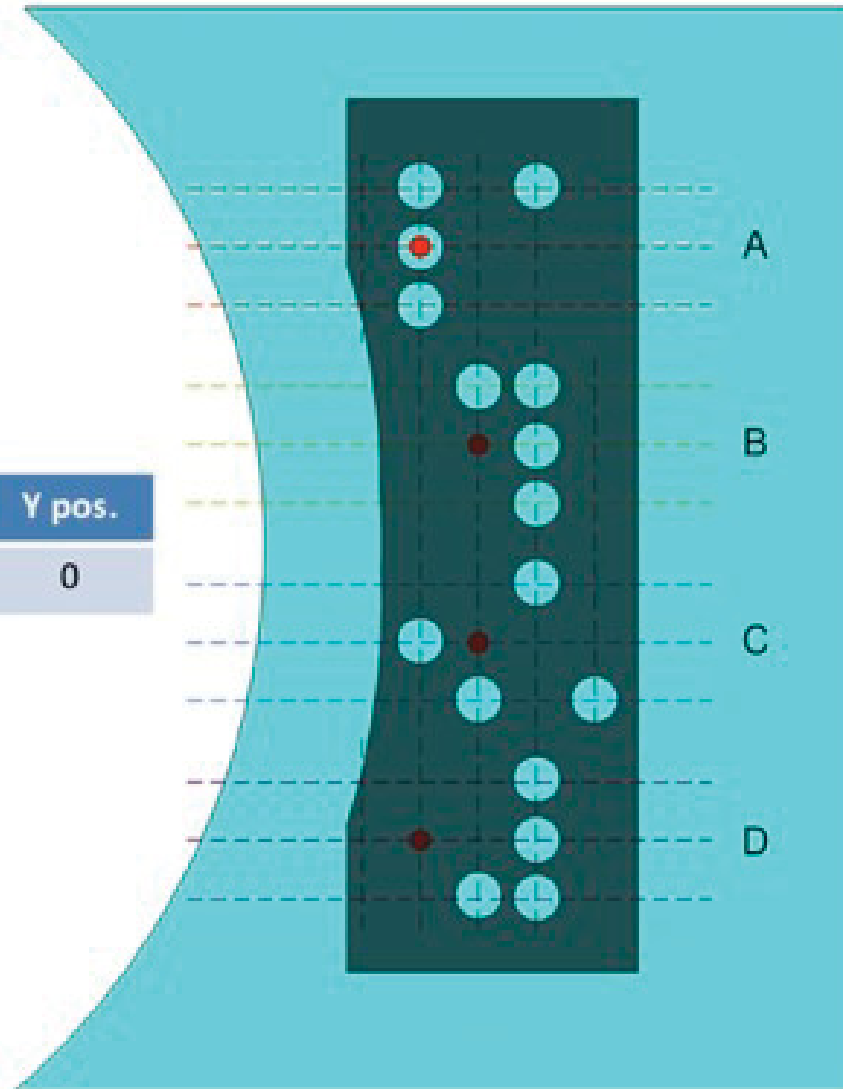
State	X pos.	Y pos.
1	0	0





Selecting the pinholes

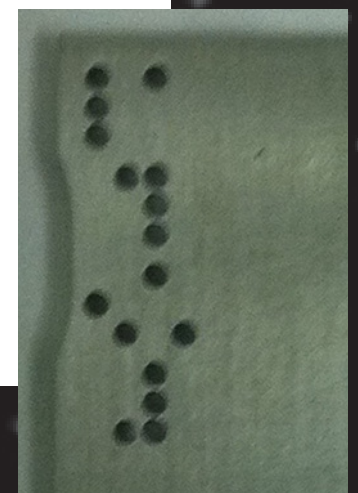
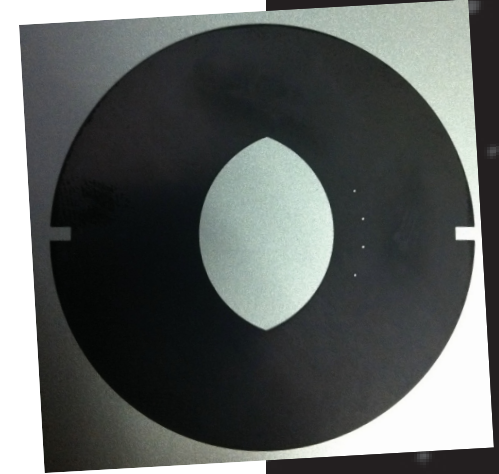
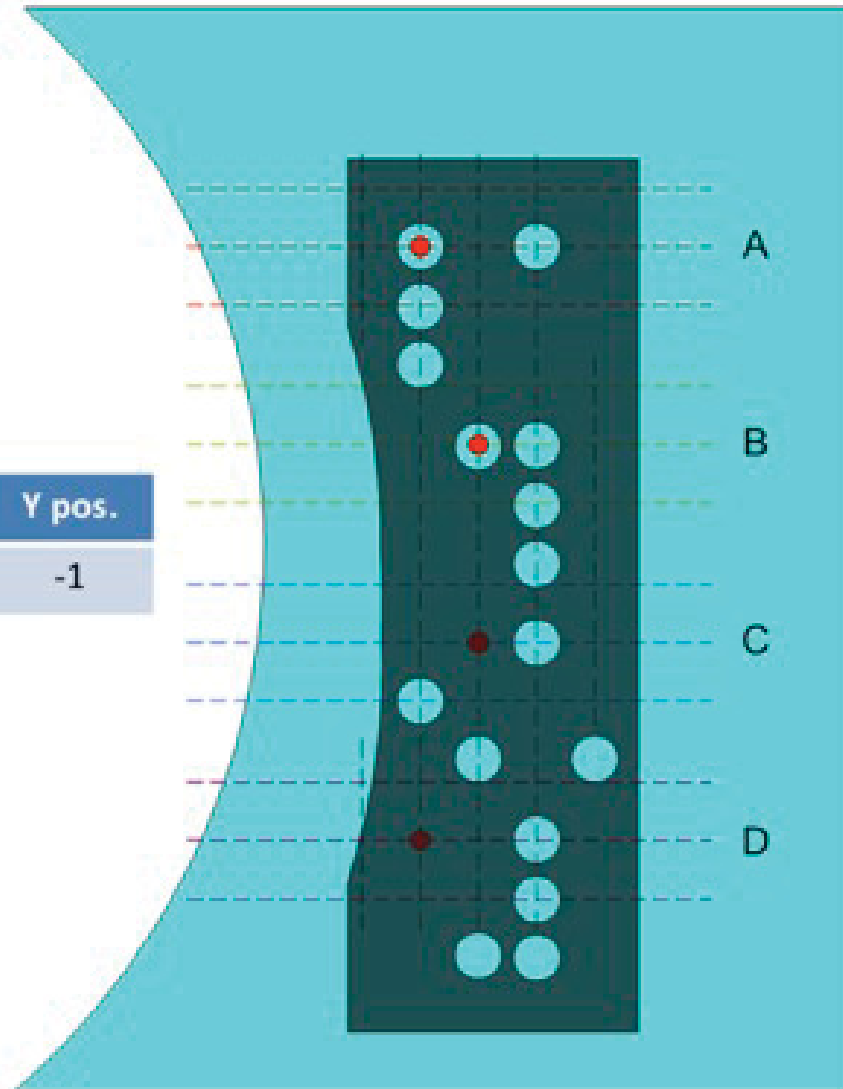
State	X pos.	Y pos.
2	1	0





Selecting the pinholes

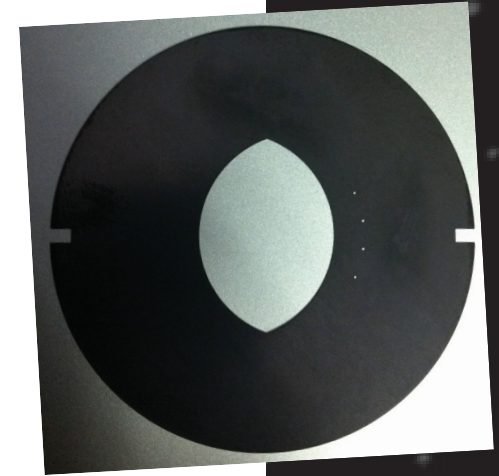
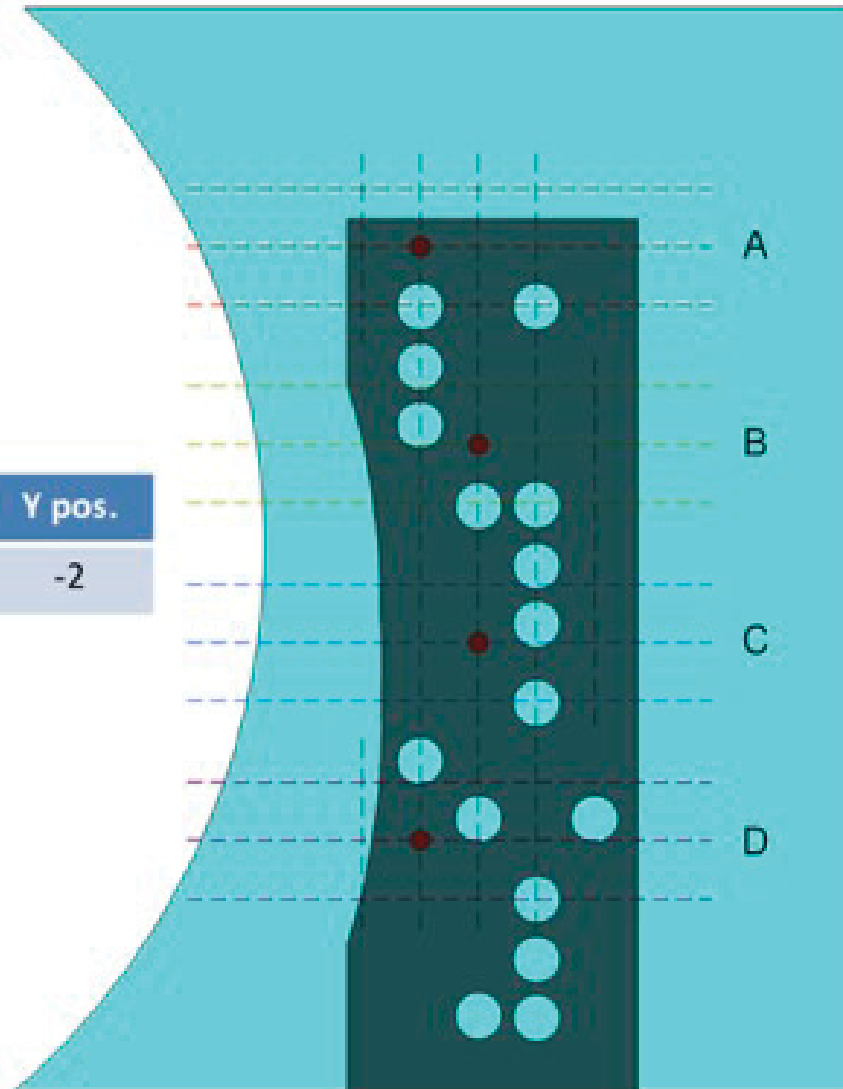
State	X pos.	Y pos.
3	1	-1





Selecting the pinholes

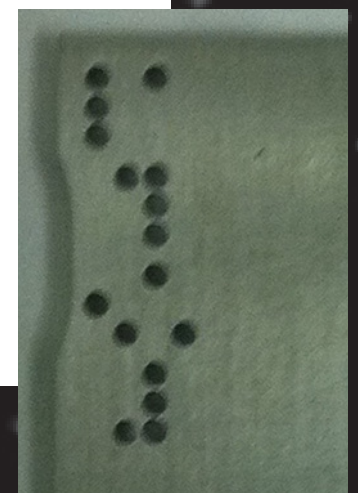
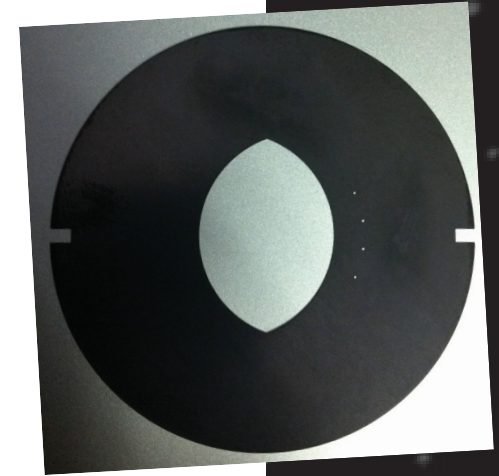
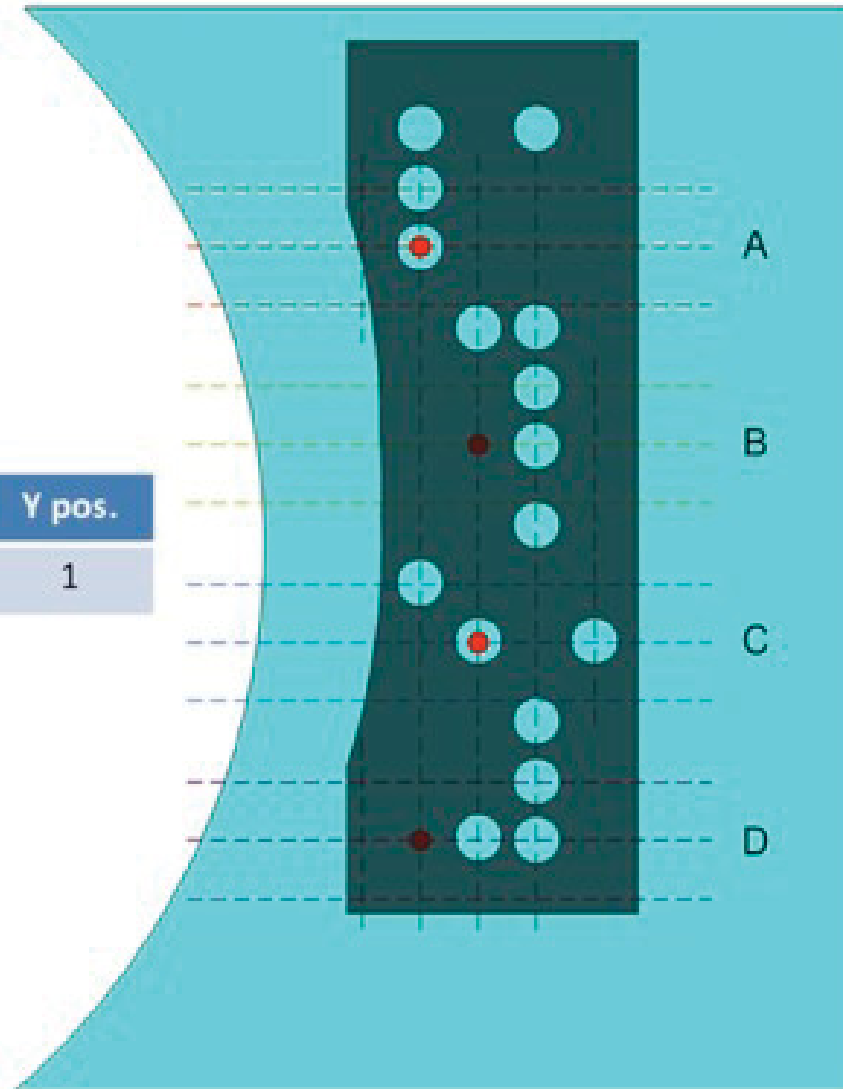
State	X pos.	Y pos.
4	1	-2





Selecting the pinholes

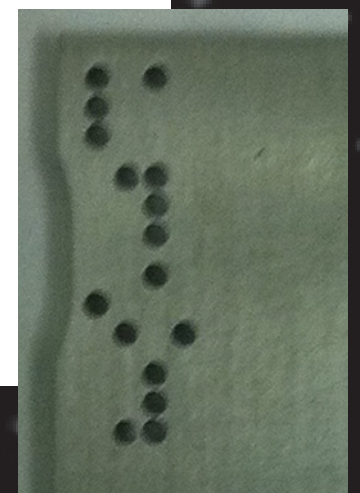
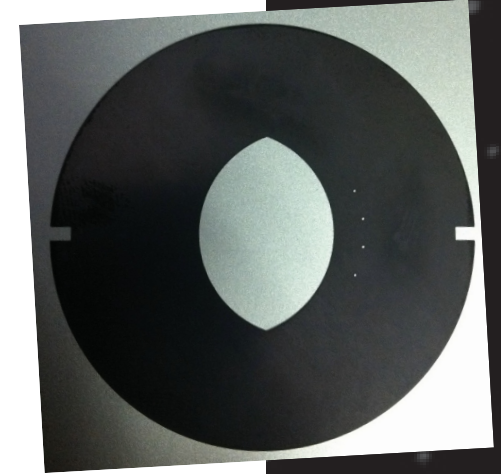
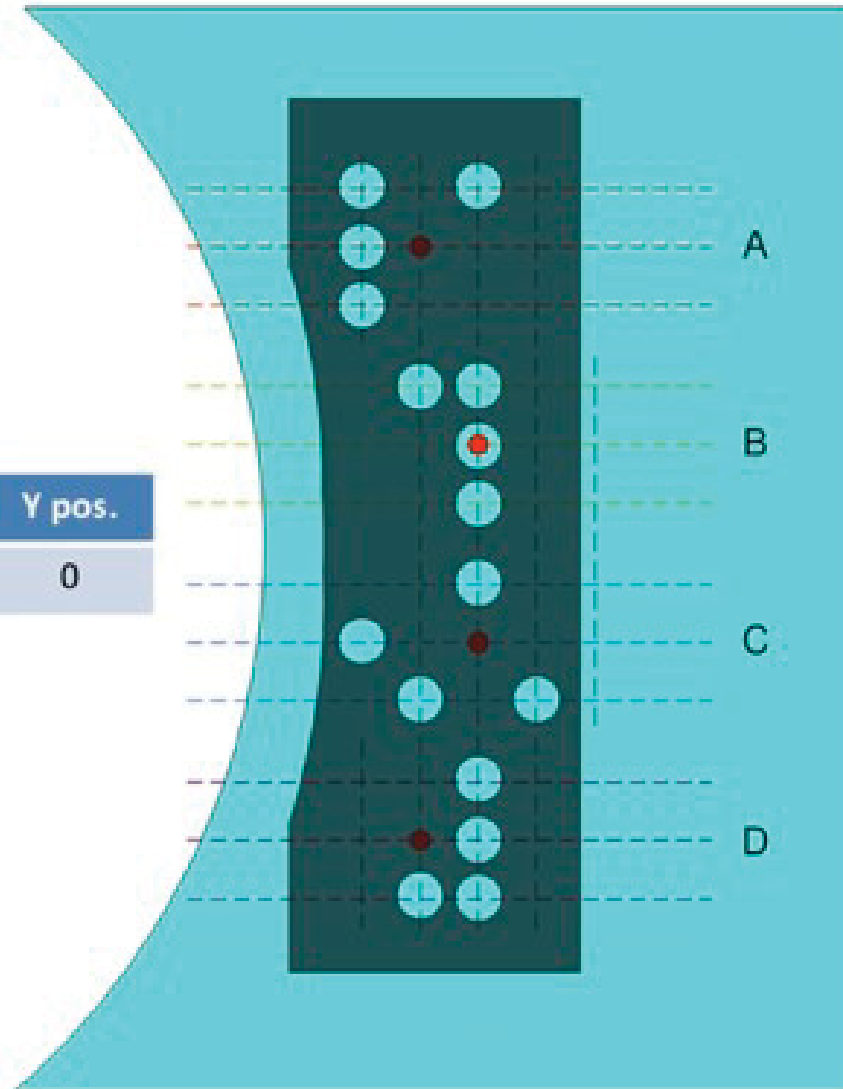
State	X pos.	Y pos.
5	1	1





Selecting the pinholes

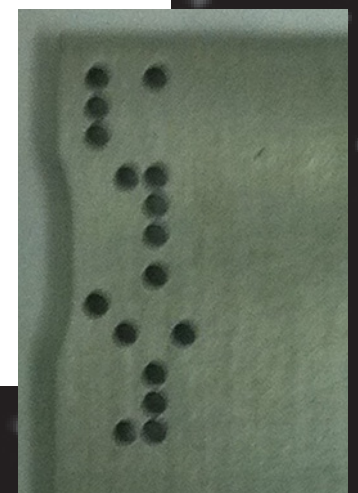
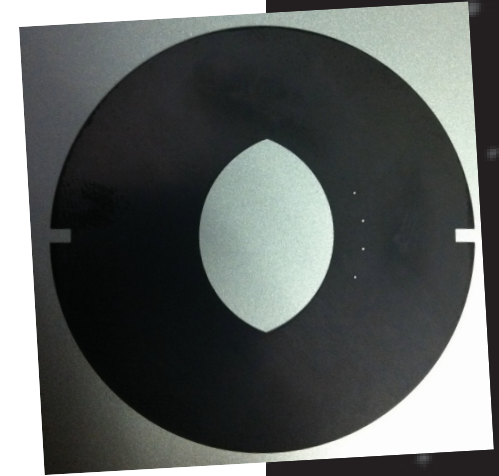
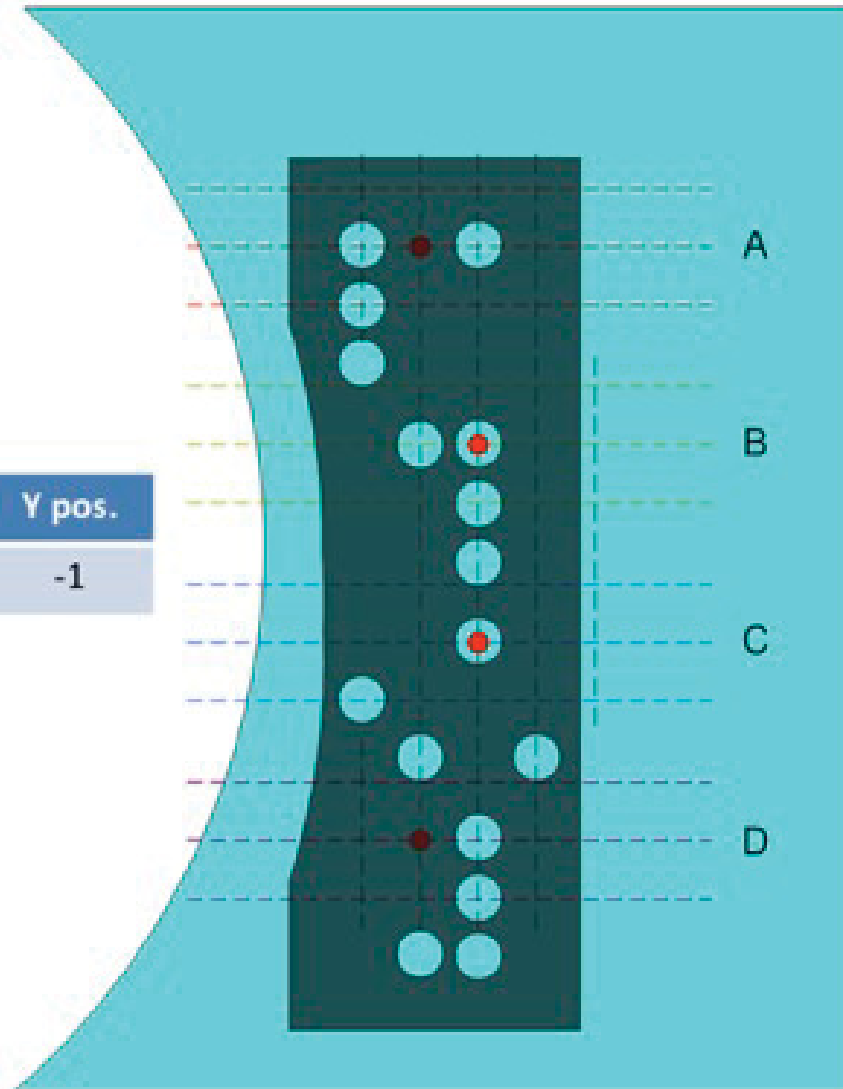
State	X pos.	Y pos.
6	2	0





Selecting the pinholes

State	X pos.	Y pos.
7	2	-1

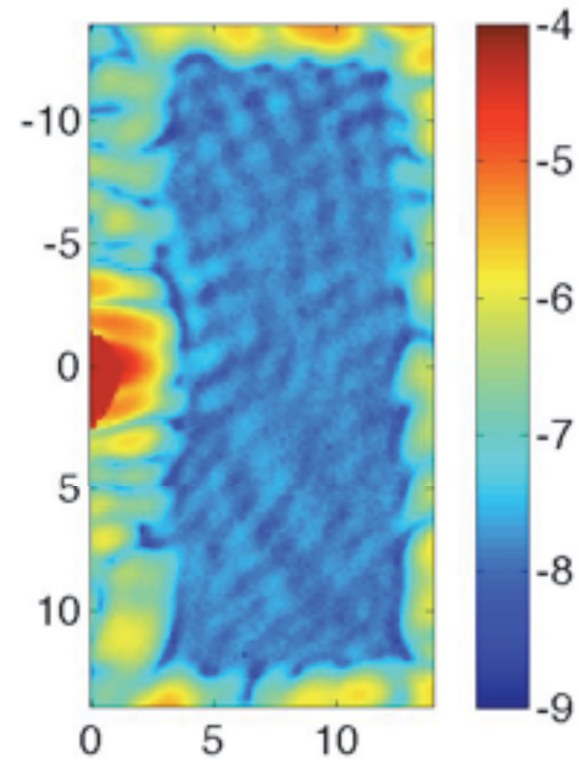
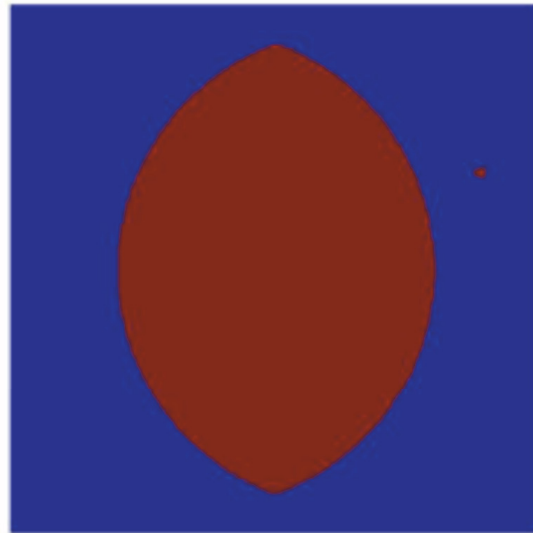




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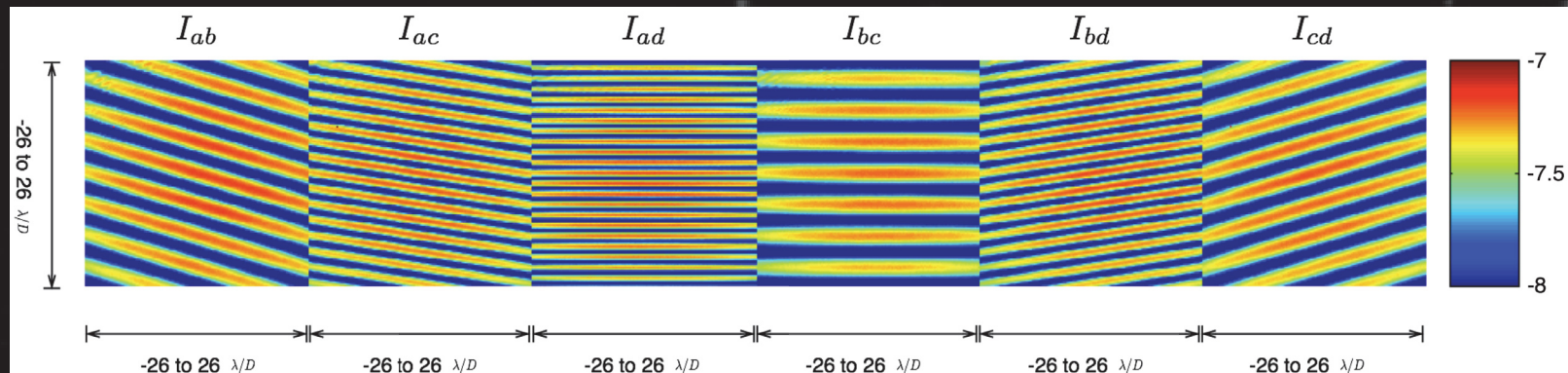
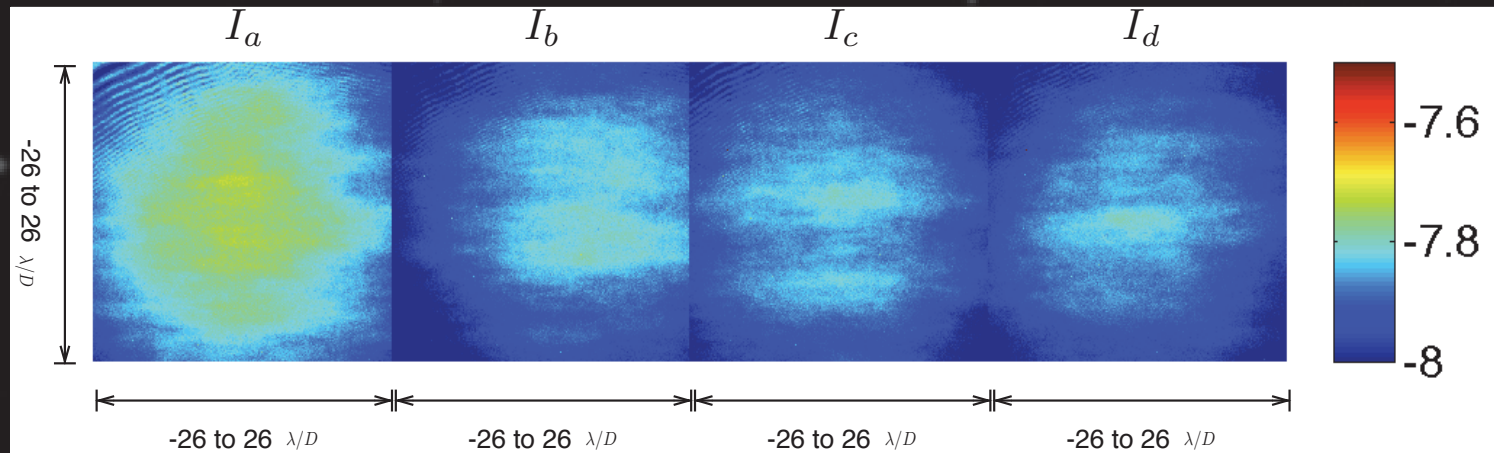
$$\begin{aligned}I_0 &= |E_0|^2 + I_{inc} \\I_{oa} &= |E_0 + E_a|^2 + I_{inc} \\I_{ob} &= |E_0 + E_b|^2 + I_{inc} \\I_{oc} &= |E_0 + E_c|^2 + I_{inc} \\I_{od} &= |E_0 + E_d|^2 + I_{inc}\end{aligned}$$

$$\begin{bmatrix} \Re\{E_0\} \\ \Im\{E_0\} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -\Im\{E_a\} & \Re\{E_a\} \\ -\Im\{E_b\} & \Re\{E_b\} \\ -\Im\{E_c\} & \Re\{E_c\} \\ -\Im\{E_d\} & \Re\{E_d\} \end{bmatrix} \begin{bmatrix} I_{oa} - |E_a|^2 \\ I_{ob} - |E_b|^2 \\ I_{oc} - |E_c|^2 \\ I_{od} - |E_d|^2 \end{bmatrix}$$



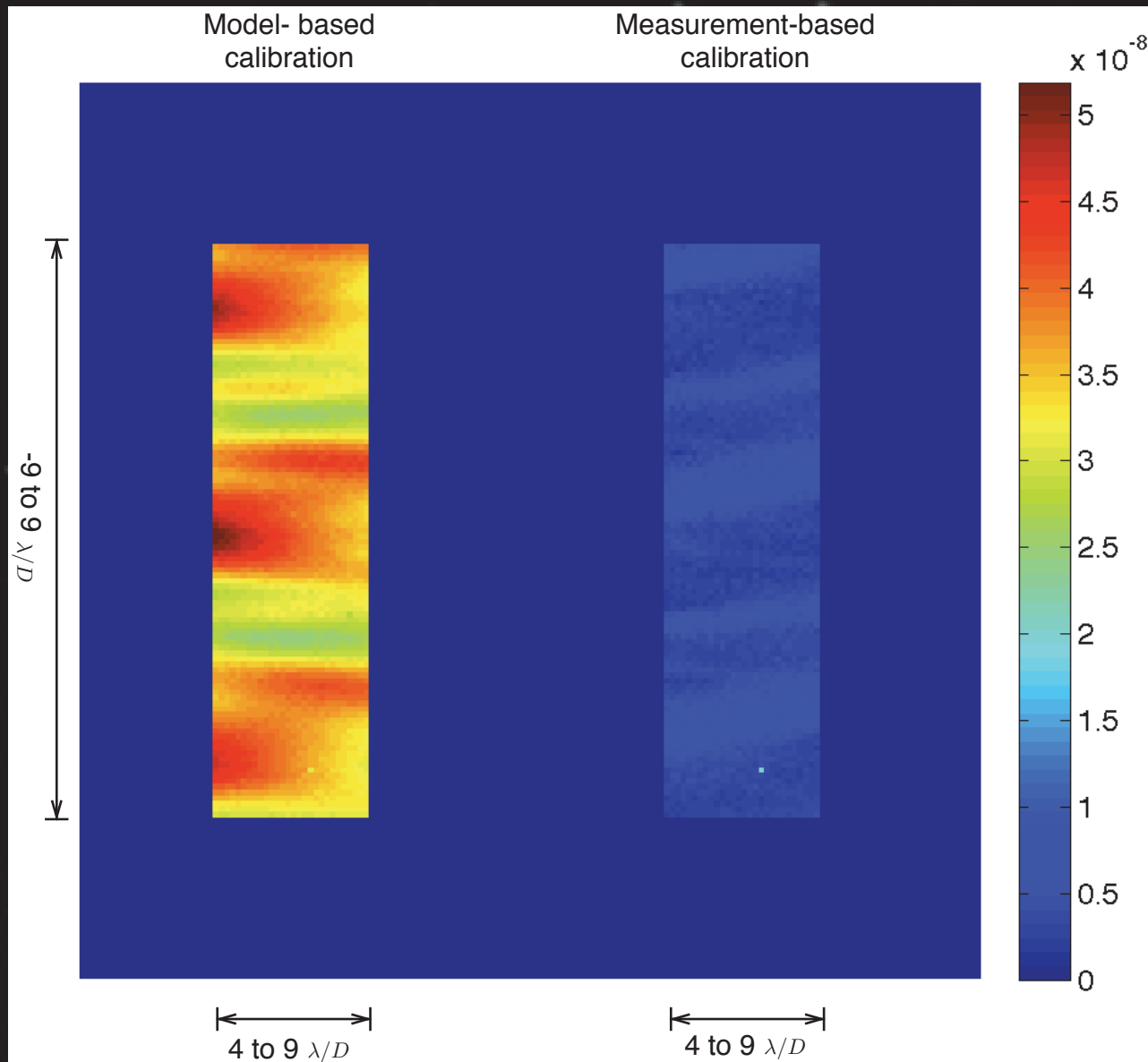
Calibration model

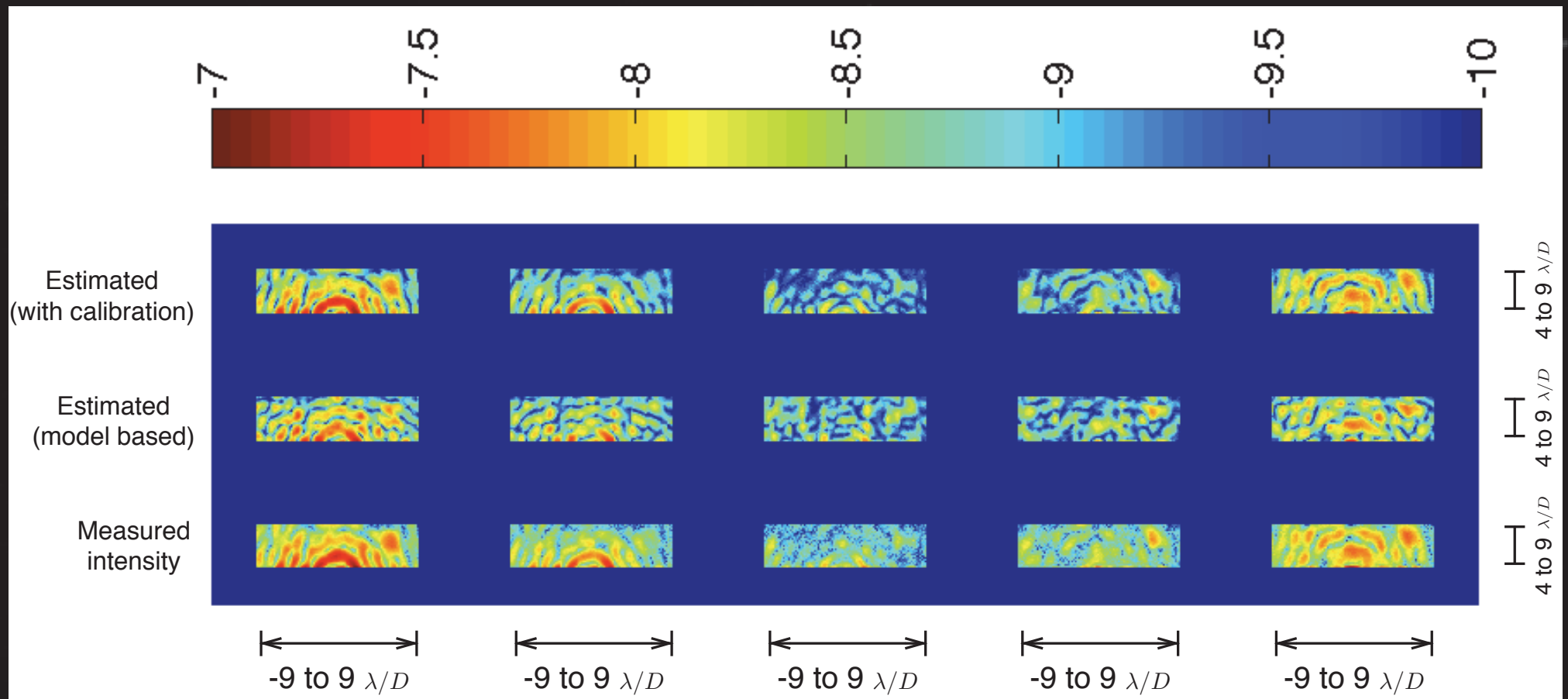
$$\begin{aligned}I_a &= |E_a|^2 \\I_b &= |E_b|^2 \\I_c &= |E_c|^2 \\I_d &= |E_d|^2 \\I_{ab} &= |E_a + E_b|^2 \\I_{ac} &= |E_a + E_c|^2 \\I_{ad} &= |E_a + E_d|^2 \\I_{bc} &= |E_b + E_c|^2 \\I_{bd} &= |E_b + E_d|^2 \\I_{cd} &= |E_c + E_d|^2\end{aligned}$$

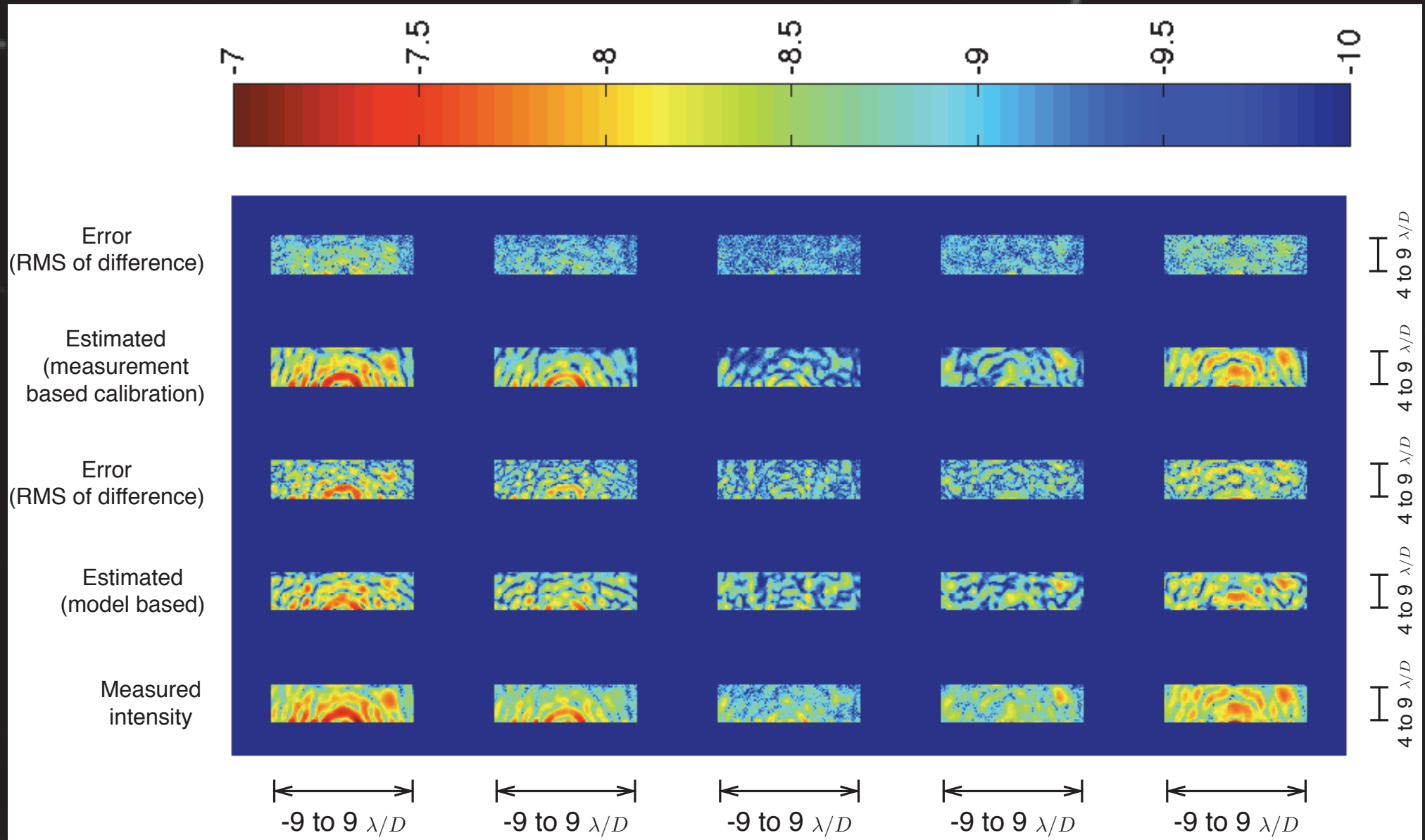




RMS improvement

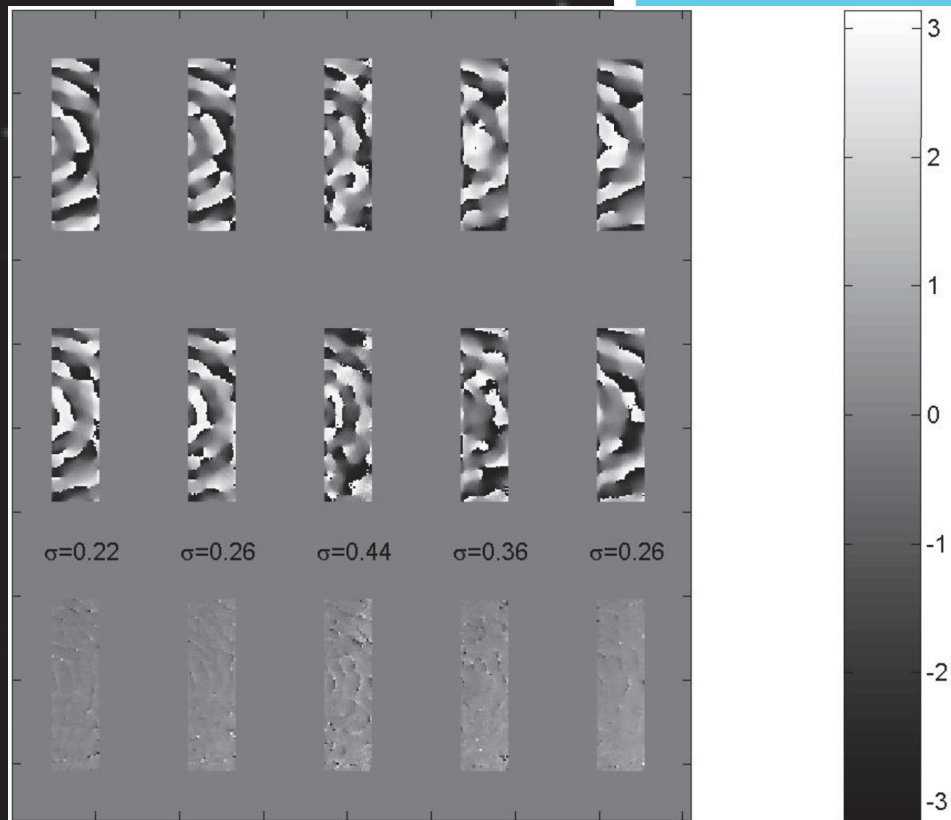
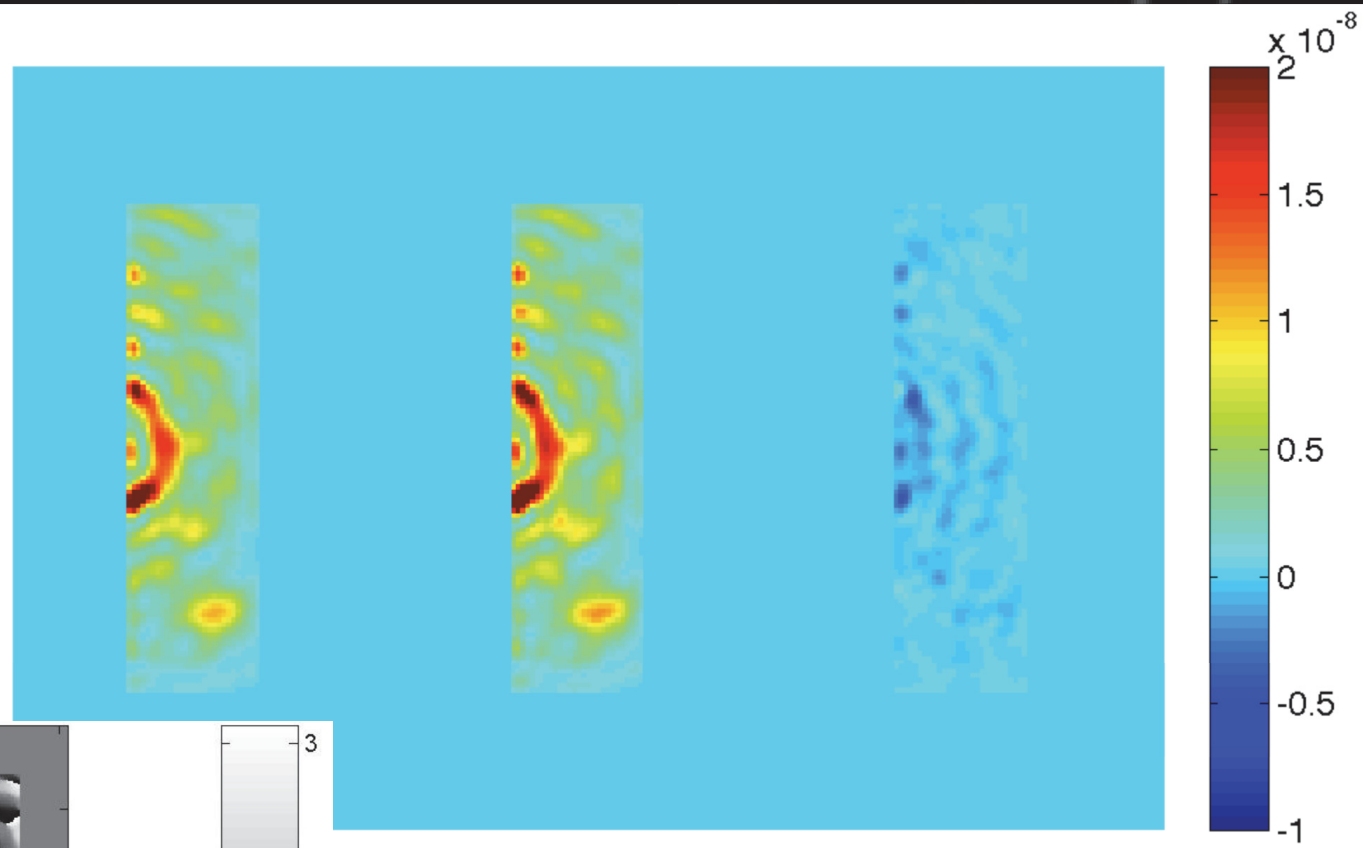








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Summary

- The pair-wise estimation has been used now on various testbeds with different coronagraphs with the best contrast results to date.
- Pinholes estimate has been implemented and ready to be tested in closed loop correction
- Pinholes estimate offers an independent method
- We hope to improve the calibration process to gain better estimates